

Solving large scale eigenvalue problems Lecture 8, April 18, 2018: Krylov spaces http://people.inf.ethz.ch/arbenz/ewp/

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Survey of today's lecture

We are back at single vector iterations. But now we want to extract more information from the data we generate.

- Krylov (sub)spaces
- Orthogonal bases for Krylov spaces

Introduction

In power method: we contruct sequence of the form (up to normalization

$$\mathbf{x}, A \mathbf{x}, A^2 \mathbf{x}, \dots$$

- Information at k-th iteration step: $\mathbf{x}^{(k)} = A^k \mathbf{x} / ||A^k \mathbf{x}||$.
- All other information discarded!
- What about keeping all the information (vectors)? More memory space required!
- Can we extract more information from all the vectors? Less computational work!

Introductory example

$$T = \left(\frac{51}{\pi}\right)^2 \begin{bmatrix} 2 & -1 & & \\ -1 & 2 & -1 & & \\ & \ddots & \ddots & \ddots & \\ & & -1 & 2 & -1 \\ & & & -1 & 2 \end{bmatrix} \in \mathbb{R}^{50 \times 50}$$

- Initial vector $\mathbf{x} = [1, \dots, 1]^*$.
- ▶ Compute first three iterates of IVI: x⁽¹⁾ = x, x⁽²⁾ = T⁻¹x, and x⁽³⁾ = T⁻²x.
- Compute Rayleigh quotients $\rho^{(i)} = \mathbf{x}^{(i)^T} T \mathbf{x}^{(i)} / \|\mathbf{x}^{(i)}\|^2$.
- ► Compute Ritz values ϑ^(k)_j obtained by Rayleigh-Ritz procedure with span(x⁽⁰⁾,...,x^(k)), k = 1, 2, 3,

Introductory example (cont.)

k	$\rho^{(k)}$	$\vartheta_1^{(k)}$	$\vartheta_2^{(k)}$	$\vartheta_3^{(k)}$
1	10.541456	10.541456		
2	1.012822	1.009851	62.238885	
3	0.999822	0.999693	9.910156	147.211990

The three smallest eigenvalues of T are 0.999684, 3.994943, and 8.974416.

The approximation errors are thus $\rho^{(3)} - \lambda_1 \approx 0.000'14$ and $\vartheta_1^{(3)} - \lambda_1 \approx 0.000'009$, which is 15 times smaller.

Results show that cost of three matrix vector multiplications can be much better exploited than with plain (inverse) vector iteration – at the expense of more memory space.

-Krylov spaces: definition and basic properties

Krylov spaces: definition and basic properties

Definition 1

Krylov matrix generated by vector $\mathbf{x} \in \mathbb{R}^n$ and A:

$$\mathcal{K}^{m}(\mathbf{x}) = \mathcal{K}^{m}(\mathbf{x}, A) := [\mathbf{x}, A\mathbf{x}, \dots, A^{m-1}\mathbf{x}] \in \mathbb{R}^{n \times m}$$
 (1)

Krylov (sub)space:

$$\mathcal{K}^m(\mathbf{x}) = \mathcal{K}^m(\mathbf{x}, A) := \operatorname{span}\left\{\mathbf{x}, A\mathbf{x}, A^2\mathbf{x}, \dots, A^{m-1}\mathbf{x}\right\} \subset \mathbb{R}^n.$$
 (2)

We can also write $\mathcal{K}_m(A, \mathbf{x}) = \{p(A)\mathbf{x} \mid p \in \mathbb{P}_{m-1}\}$ where \mathbb{P}_d denotes set of polynomials of degree at most d.

-Krylov spaces: definition and basic properties

Krylov spaces: definition and basic properties (cont.)

The Arnoldi and Lanczos algorithms are methods to compute an orthonormal basis of the Krylov space. Let

$$\left[\mathbf{x}, A\mathbf{x}, \dots, A^{k-1}\mathbf{x}\right] = Q^{(k)}R^{(k)}$$

be QR factorization of Krylov matrix $K^m(\mathbf{x}, A)$. The Ritz values and Ritz vectors of A in $K^m(\mathbf{x}, A)$ are obtained by means of the $k \times k$ eigenvalue problem

$$Q^{(k)*}AQ^{(k)}\mathbf{y} = \vartheta^{(k)}\mathbf{y}.$$
(3)

If $(\vartheta_j^{(k)}, \mathbf{y}_j)$ is an eigenpair of (3) then $(\vartheta_j^{(k)}, Q^{(k)}\mathbf{y}_j)$ is a Ritz pair of A in $K^m(\mathbf{x})$.

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-Krylov spaces: definition and basic properties

Krylov spaces: definition and basic properties (cont.) Simple properties of Krylov spaces [2, p.238]

- 1. Scaling. $\mathcal{K}^{m}(\mathbf{x}, A) = \mathcal{K}^{m}(\alpha \mathbf{x}, \beta A), \quad \alpha, \beta \neq 0.$
- 2. Translation. $\mathcal{K}^m(\mathbf{x}, A \sigma \mathbf{I}) = \mathcal{K}^m(\mathbf{x}, A)$.
- 3. Change of basis. If U is unitary then $U\mathcal{K}^m(U^*\mathbf{x}, U^*AU) = \mathcal{K}^m(\mathbf{x}, A).$ In fact,

$$\begin{aligned} \mathcal{K}^{m}(\mathbf{x},A) &= [\mathbf{x},A\mathbf{x},\ldots,A^{m-1}\mathbf{x}] \\ &= U[U^{*}\mathbf{x},(U^{*}AU)U^{*}\mathbf{x},\ldots,(U^{*}AU)^{m-1}U^{*}\mathbf{x}], \\ &= U\mathcal{K}^{m}(U^{*}\mathbf{x},U^{*}AU). \end{aligned}$$

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Notice that the scaling and translation invariance hold only for the Krylov subspace, not for the Krylov matrices.

-Krylov spaces: definition and basic properties

Dimension of $\mathcal{K}^k(\mathbf{x}, A)$

What is the dimension of $\mathcal{K}^k(\mathbf{x})$?

Clearly, dim $(\mathcal{K}^k(\mathbf{x})) \leq k \leq n$.

There must be a *m* for which $\mathcal{K}_1 \subsetneqq \mathcal{K}_2 \gneqq \cdots \subsetneqq \mathcal{K}_m = \mathcal{K}_{m+1} = \cdots$ We have

$$A^{m}\mathbf{x} = \alpha_0 \mathbf{x} + \alpha_1 A \mathbf{x} + \alpha_2 A^2 \mathbf{x} + \dots + \alpha_{p-1} A^{m-1} \mathbf{x}$$

Thus, $K^{m+1}(\mathbf{x})$ has linearly depending columns.

If we reach m there cannot be a further increase of dimension later.

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-Krylov spaces: definition and basic properties

Dimension of $\mathcal{K}^{k}(\mathbf{x}, A)$ (cont.) Let A be diagonalizable and $\mathbf{x} = \sum_{i=1}^{m} \mathbf{q}_{i}$, where $A\mathbf{q}_{i} = \lambda_{i}\mathbf{q}_{i}, \mathbf{q}_{i} \neq \mathbf{0}$, with distinct λ_{i} . Then,

$$\underbrace{[\mathbf{x}, A\mathbf{x}, \cdots, A^{k}\mathbf{x}]}_{n \times (k+1)} = \underbrace{[\mathbf{q}_{1}, \mathbf{q}_{2}, \cdots, \mathbf{q}_{m}]}_{n \times m} \underbrace{\begin{bmatrix} 1 & \lambda_{1} & \cdots & \lambda_{1}^{k} \\ 1 & \lambda_{2} & \cdots & \lambda_{2}^{k} \\ \vdots & \vdots & \vdots \\ 1 & \lambda_{m} & \cdots & \lambda_{m}^{k} \end{bmatrix}}_{m \times (k+1)}$$

For k < m, the $m \times (k+1)$ matrix on the right has linearly independent columns. (Relation to *Vandermonde* matrices!)

$$\dim \mathcal{K}^k(\mathbf{x}, A) = \min\{k, m\}$$

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Polynomial basis for \mathcal{K}^m

Now we assume A to be Hermitian. Let $\mathbf{s} \in \mathcal{K}^{j}(\mathbf{x})$. Then

$$\mathbf{s} = \sum_{i=0}^{j-1} c_i A^i \mathbf{x} = \pi(A) \mathbf{x}, \qquad \pi(\xi) = \sum_{i=0}^{j-1} c_i \xi^i.$$

Let \mathbb{P}_j be the space of polynomials of degree $\leq j$. Then

$$\mathcal{K}^{j}(\mathbf{x}) = \{\pi(A)\mathbf{x} \mid \pi \in \mathbb{P}_{j-1}\}.$$

Let *m* be the smallest index for which $\mathcal{K}^m(\mathbf{x}) = \mathcal{K}^{m+1}(\mathbf{x})$. Then,

$$\mathbb{P}^{j-1} \ni \sum c_i \xi^i \to \sum c_i A^i \mathbf{x} \in \mathcal{K}^j(\mathbf{x})$$

is bijective for $j \leq m$, while it is only surjective for j > m.

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Polynomial basis for \mathcal{K}^m (cont.)

Let $Q \in \mathbb{R}^{n \times j}$ be matrix with orthonormal basis of $\mathcal{K}^{j}(\mathbf{x})$ Let $\tilde{A} = Q^{*}AQ$. The spectral decomposition

$$ilde{A} ilde{X} = ilde{X}\Theta, \qquad ilde{X}^* ilde{X} = I, \quad \Theta = \mathsf{diag}(artheta_i, \dots, artheta_j),$$

of \tilde{A} provides the Ritz values of A in $\mathcal{K}^{j}(\mathbf{x})$. The columns \mathbf{y}_{i} of $Y = Q\tilde{X}$ are the Ritz vectors.

By construction the Ritz vectors are mutually orthogonal.

Furthermore,

$$A\mathbf{y}_i - \vartheta_i \mathbf{y}_i \perp \mathcal{K}^j(\mathbf{x}) \tag{4}$$

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Polynomial basis for \mathcal{K}^m (cont.)

It is easy to represent a vector in $\mathcal{K}^{j}(\mathbf{x})$ that is orthogonal to \mathbf{y}_{i} .

Lemma 2

Let $(\vartheta_i, \mathbf{y}_i)$, $1 \leq i \leq j$ be Ritz values and Ritz vectors of A in $\mathcal{K}^j(\mathbf{x}), j \leq m$. Let $\omega \in \mathbb{P}_{j-1}$. Then

$$\omega(A)\mathbf{x} \perp \mathbf{y}_k \iff \omega(\vartheta_k) = 0.$$
 (*)

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-Polynomial basis for \mathcal{K}^m

Polynomial basis for \mathcal{K}^m (cont.)

Proof. "
$$\Leftarrow$$
"
Let $\omega \in \mathbb{P}_j$ with $\omega(x) = (x - \vartheta_k)\pi(x), \pi \in \mathbb{P}_{j-1}$. Then

$$\mathbf{y}_{k}^{*}\omega(A)\mathbf{x} = \mathbf{y}_{k}^{*}(A - \vartheta_{k}\mathbf{I})\pi(A)\mathbf{x}, \quad \text{here we use that } A = A^{*}$$
$$= (A\mathbf{y}_{k} - \vartheta_{k}\mathbf{y}_{k})^{*}\pi(A)\mathbf{x} \stackrel{(4)}{=} 0.$$
(5)

"⇒" Let $\mathcal{S}_k \subset \mathcal{K}^j(\mathbf{x})$ be defined by

$$\mathcal{S}_k := \left(\mathsf{A} - artheta_k \mathsf{I}
ight) \mathcal{K}^{j-1}(\mathbf{x}) = \left\{ au(\mathsf{A})\mathbf{x} \mid au \in \mathbb{P}_{j-1}, au(artheta_k) = \mathsf{0}
ight\},$$

(5) \implies \mathbf{y}_k is orthogonal to \mathcal{S}_k . \mathcal{S}_k has dimension j-1. As the dimension of a subspace of $\mathcal{K}^j(\mathbf{x})$ that is orthogonal to \mathbf{y}_k is j-1, it must coincide with \mathcal{S}_k .

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Polynomial basis for \mathcal{K}^m (cont.)

We define the polynomials

$$\mu(\xi) := \prod_{i=1}^{j} (\xi - \vartheta_i) \in \mathbb{P}_j, \quad \pi_k(\xi) := \frac{\mu(\xi)}{(\xi - \vartheta_k)} = \prod_{\substack{i=1\\i \neq k}}^{j} (\xi - \vartheta_i) \in \mathbb{P}_{j-1}.$$

(Normalized) Ritz vector \mathbf{y}_k can be represented in the form

$$\mathbf{y}_{k} = \frac{\pi_{k}(A)\mathbf{x}}{\|\pi_{k}(A)\mathbf{x}\|},\tag{6}$$

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as $\pi_k(\vartheta_i) = 0$ for all $i \neq k$. According to the Lemma $\pi_k(A)\mathbf{x}$ is perpendicular to all \mathbf{y}_i with $i \neq k$.

-Polynomial basis for \mathcal{K}^m

Polynomial basis for \mathcal{K}^m (cont.)

By the first part of Lemma 2 $\mu(A)\mathbf{x} \in \mathcal{K}^{j+1}(\mathbf{x})$ is orthogonal to $\mathcal{K}^{j}(\mathbf{x})$. As each monic $\omega \in \mathbb{P}_{j}$ can be written in the form

$$\omega(\xi) = \mu(\xi) + \psi(\xi), \qquad \psi \in \mathbb{P}_{j-1},$$

we have

$$\|\omega(A)\mathbf{x}\|^2 = \|\mu(A)\mathbf{x}\|^2 + \|\psi(A)\mathbf{x}\|^2,$$

as
$$\psi({\mathsf{A}}){\mathsf{x}}\in\mathcal{K}^j({\mathsf{x}}).$$

Let $\mathbf{u}_1, \dots, \mathbf{u}_m$ be the eigenvectors of A corresponding to $\lambda_1 < \dots < \lambda_m$ that span $\mathcal{K}^m(\mathbf{x})$.

Let
$$\|\mathbf{x}\| = 1$$
. Let $\varphi := \angle(\mathbf{x}, \mathbf{u}_1)$. Then

$$\|\mathbf{u}_1\mathbf{u}_1^*\mathbf{x}\| = \cos \varphi, \qquad \|(\mathbf{I} - \mathbf{u}_1\mathbf{u}_1^*)\mathbf{x}\| = \sin \varphi.$$

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-Polynomial basis for \mathcal{K}^m

Polynomial basis for
$$\mathcal{K}^m$$
 (cont.)
Let $\mathbf{h} := (I - \mathbf{u}_1 \mathbf{u}_1^*) \mathbf{x} / \| (I - \mathbf{u}_1 \mathbf{u}_1^*) \mathbf{x} \|$.

Lemma 3 (Parlett [2])

For each $\pi \in \mathbb{P}_{j-1}$ the Rayleigh quotient

$$\rho(\pi(A)\mathbf{x}; A - \lambda_1 I) = \rho(\pi(A)\mathbf{x}; A) - \lambda_1 = \frac{(\pi(A)\mathbf{x})^*(A - \lambda_1 I)(\pi(A)\mathbf{x})}{\|\pi(A)\mathbf{x}\|^2}$$

satisfies the inequality

$$o(\pi(A)\mathbf{x}; A - \lambda_1 I) \leq (\lambda_m - \lambda_1) igg[an arphi \, rac{\|\pi(A)\mathbf{h}\|}{\pi(\lambda_1)} igg]^2$$

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Polynomial basis for \mathcal{K}^m (cont.)

Proof.

With \mathbf{h} from above we have the orthogonal decompositions

$$\mathbf{x} = \mathbf{u}_1 \mathbf{u}_1^* \mathbf{x} + (I - \mathbf{u}_1 \mathbf{u}_1^*) \mathbf{x} = \cos \varphi \ \mathbf{u}_1 + \sin \varphi \ \mathbf{h}$$

and

$$\mathbf{s} := \pi(A)\mathbf{x} = \cos \varphi \ \pi(A)\mathbf{u}_1 + \sin \varphi \ \pi(A)\mathbf{h}.$$

Thus,

$$\rho(\mathbf{s}; A - \lambda_1 I) = \frac{\cos^2 \varphi \, \mathbf{u}_1^* (A - \lambda_1 I) \pi^2 (A) \mathbf{u}_1 + \sin^2 \varphi \, \mathbf{h}^* (A - \lambda_1 I) \pi^2 (A) \mathbf{h}}{\|\mathbf{s}\|^2}$$
$$\overset{(A\mathbf{u}_1 = \lambda_1 \mathbf{u}_1)}{=} \frac{\sin^2 \varphi \, \mathbf{h}^* (A - \lambda_1 I) \pi^2 (A) \mathbf{h}}{\|\mathbf{s}\|^2}.$$

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Polynomial basis for \mathcal{K}^m (cont.)

Since $\lambda_1 < \lambda_2 < \cdots < \lambda_m$, we have

$$\mathbf{w}^*(A - \lambda_1 I)\mathbf{w} \leq (\lambda_m - \lambda_1) \|\mathbf{w}\|^2$$
 for all $\mathbf{w} \in \mathcal{R}(\mathbf{u}_1)^{\perp}$

Setting $\mathbf{w} = \pi(A)\mathbf{h}$ we obtain

$$\rho(\mathbf{s}; A - \lambda_1 I) \leq \sin^2 \varphi \left(\lambda_m - \lambda_1\right) \frac{\|\pi(A)\mathbf{h}\|^2}{\|\pi(A)\mathbf{x}\|^2}.$$

With

$$\|\mathbf{s}\|^2 = \|\pi(A)\mathbf{x}\|^2 = \sum_{\ell=1}^m \pi^2(\lambda_\ell)(\mathbf{x}^*\mathbf{u}_\ell)^2 \ge \pi^2(\lambda_1)\cos^2\varphi$$

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we obtain the claim.

Error bounds by Saad

- For simplicity we consider convergence of Ritz values θ₁^(j) to λ₁.
- The error bounds to be presented have been published by Saad [3]. We follow the presentation in Parlett [3].
- ► The error bounds for ϑ^(j)₁ − λ₁ are obtained by carefully selecting the polynomial π in Lemma 3.
- Of course we would like π(A) to be as small as possible and π(λ₁) to be as large as possible.

Error bounds by Saad (cont.)

First, by the definition of \mathbf{h} , we have

$$\begin{aligned} \|\pi(A)\mathbf{h}\|^{2} &= \frac{\|\pi(A)(I - \mathbf{u}_{1}\mathbf{u}_{1}^{*})\mathbf{x}\|^{2}}{\|(I - \mathbf{u}_{1}\mathbf{u}_{1}^{*})\mathbf{x}\|^{2}} = \frac{\|\pi(A)\sum_{\ell=2}^{m}(\mathbf{u}_{\ell}^{*}\mathbf{x})\mathbf{u}_{\ell}\|^{2}}{\|\sum_{\ell=2}^{m}(\mathbf{u}_{\ell}^{*}\mathbf{x})\mathbf{u}_{\ell}\|^{2}} \\ &= \frac{\sum_{\ell=2}^{m}(\mathbf{u}_{\ell}^{*}\mathbf{x})^{2}\pi^{2}(\lambda_{\ell})}{\sum_{\ell=2}^{m}(\mathbf{u}_{\ell}^{*}\mathbf{x})^{2}} \leq \max_{2\leq\ell\leq m}\pi^{2}(\lambda_{\ell})\leq \max_{\lambda_{2}\leq\lambda\leq\lambda_{m}}\pi^{2}(\lambda). \end{aligned}$$

The last inequality is important! In this step the search of a maximum in a few selected points $(\lambda_2, \ldots, \lambda_m)$ is replaced by a search of a maximum in a *whole interval* containing these points.

Notice that λ_1 is *outside* of this interval.

Error bounds by Saad (cont.)

Among all polynomials of given degree that take a fixed value $\pi(\lambda_1)$ the Chebyshev polynomial has the smallest maximum.

$$\begin{split} \min_{\pi \in \mathbb{P}_{j-1}} \max_{\lambda_2 \leq \lambda \leq \lambda_m} \frac{|\pi(\lambda)|}{|\pi(\lambda_1)|} &= \frac{\max_{\lambda_2 \leq \lambda \leq \lambda_m} T_{j-1}(\lambda; [\lambda_2, \lambda_m])}{T_{j-1}(\lambda_1; [\lambda_2, \lambda_m])} \\ &= \frac{1}{T_{j-1}(\lambda_1; [\lambda_2, \lambda_m])} \\ &= \frac{1}{T_{j-1}(1+2\gamma)}, \qquad \gamma = \frac{\lambda_2 - \lambda_1}{\lambda_m - \lambda_2}. \end{split}$$

 $T_{j-1}(1+2\gamma)$ is the value of the Chebyshev polynomial corresponding to the 'normal' interval [-1, 1].

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Error bounds by Saad (cont.)

The point $1+2\gamma$ is obtained if the affine transformation

$$[\lambda_2, \lambda_m] \ni \lambda \longrightarrow \frac{2\lambda - \lambda_2 - \lambda_m}{\lambda_1 - \lambda_2} \in [-1, 1]$$

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is applied to λ_1 .

Error bounds by Saad (cont.)

Thus we have proved the first part of the following

Theorem 4 (Saad [3])

Let $\vartheta_1^{(j)}, \ldots, \vartheta_j^{(j)}$ be the Ritz values of A in $\mathcal{K}^j(\mathbf{x})$ and let $(\lambda_\ell, \mathbf{u}_\ell), \ \ell = 1, \ldots, m$, be the eigenpairs of A (in $\mathcal{K}^m(\mathbf{x})$). Then

$$0 \leq \vartheta_1^{(j)} - \lambda_1 \leq (\lambda_m - \lambda_1) \left[\tan \varphi \frac{1}{T_{j-1}(1+2\gamma)} \right]^2, \quad \gamma = \frac{\lambda_2 - \lambda_1}{\lambda_m - \lambda_2},$$

and

$$an \angle (\mathbf{u}_1, ext{projection of } \mathbf{u}_1 ext{ on } \mathcal{K}^j) \leq an arphi \cdot rac{1}{\mathcal{T}_{j-1}(1+2\gamma)}.$$

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Error bounds by Saad (cont.)

Proof. For proving the second part of the Theorem we write

 $\mathbf{x} = \mathbf{u}_1 \cos \varphi + \mathbf{h} \sin \varphi.$

Then

$$\mathbf{s} = \pi(A)\mathbf{x} = \pi(\lambda_1)\mathbf{u}_1\cos\varphi + \pi(A)\mathbf{h}\sin\varphi$$

is an orthogonal decomposition of \mathbf{s} . By consequence,

$$an \angle (\mathbf{s}, \mathbf{u}_1) = rac{\sin arphi \| \pi(A) \mathbf{h} \|}{\cos arphi | \pi(\lambda_1) |}.$$

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The rest is similar as above.

Error bounds by Saad (cont.)

Theorem 4 can be rewritten to give error bounds for $\lambda_m - \vartheta_j^{(j)}$ but also for the interior eigenvalues, see lecture notes. For the largest eigenvalue we have

$$0 \le \lambda_m - \vartheta_j^{(j)} \le (\lambda_m - \lambda_1) \tan^2 \varphi_m \frac{1}{T_{j-1}(1 + 2\gamma_m)^2}, \quad (7)$$

with

$$\gamma_m = \frac{\lambda_m - \lambda_{m-1}}{\lambda_{m-1} - \lambda_1}, \text{ and } \cos \varphi_m = \mathbf{x}^* \mathbf{u}_m.$$

From more general results one sees that the eigenvalues at the beginning and at the end of the spectrum are approximated the quickest.

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Error bounds by Saad

Error bounds by Saad (cont.)

If the Lanczos algorithmus is applied with $(A - \sigma I)^{-1}$ then we form Krylov spaces $\mathcal{K}^{j}(\mathbf{x}, (A - \sigma I)^{-1})$. Here the eigenvalues are $\frac{1}{\hat{\lambda}_{1}} \geq \frac{1}{\hat{\lambda}_{2}} \geq \cdots \geq \frac{1}{\hat{\lambda}_{m}}, \quad \hat{\lambda}_{i} = \lambda_{i} - \sigma.$ Eq. (7) then becomes

$$0 \leq \frac{1}{\hat{\lambda}_1} - \frac{1}{\hat{\vartheta}_m^{(j)}} \leq (\frac{1}{\hat{\lambda}_1} - \frac{1}{\hat{\lambda}_m}) \frac{\tan^2 \varphi_1}{T_{j-1}(1+2\hat{\gamma}_1)^2}, \quad \hat{\gamma}_1 = \frac{\frac{1}{\hat{\lambda}_1} - \frac{1}{\hat{\lambda}_2}}{\frac{1}{\hat{\lambda}_2} - \frac{1}{\hat{\lambda}_m}}.$$

One can show that

$$1+2\hat{\gamma}_1=2(1+\hat{\gamma}_1)-1\geq 2rac{\hat{\lambda}_2}{\hat{\lambda}_1}-1>1.$$

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Error bounds by Saad

Error bounds by Saad (cont.)

Since $|T_{j-1}(\xi)|$ grows rapidly and monotonically outside [-1, 1] we have

$$extsf{T}_{j-1}(1+2\hat{\gamma}_1)\geq extsf{T}_{j-1}(2rac{\lambda_2}{\hat{\lambda}_1}-1),$$

and thus

$$\frac{1}{\hat{\lambda}_1} - \frac{1}{\hat{\vartheta}_1^{(j)}} \le c_1 \left(\frac{1}{T_{j-1}(2\frac{\hat{\lambda}_2}{\hat{\lambda}_1} - 1)} \right)^2$$
(8)

With the simple inverse vector iteration we had

$$\frac{1}{\hat{\lambda}_1} - \frac{1}{\hat{\lambda}_1^{(j)}} \le c_2 \left(\frac{\hat{\lambda}_1}{\hat{\lambda}_2}\right)^{2(j-1)} \tag{9}$$

Error bounds by Saad

Error bounds by Saad (cont.)

$\frac{\hat{\lambda}_2}{\hat{\lambda}_1}$	<i>j</i> = 5	<i>j</i> = 10	<i>j</i> = 15	<i>j</i> = 20	<i>j</i> = 25
2.0	<u>3.00<i>e</i> - 06</u> 3.91 <i>e</i> - 03	<u>6.63e - 14</u> 3.81e - 06	<u>1.46e — 21</u> 3.72e — 09	<u>3.24e – 29</u> 3.63e – 12	<u>7.17e — 37</u> 3.55e — 15
1.1	<u>2.71e - 02</u> 4.66e - 01	<u>5.45e - 05</u> 1.79e - 01	<u>1.08e - 07</u> 6.93e - 02	<u>2.14e - 10</u> 2.67e - 02	$rac{4.24e-13}{1.03e-02}$
1.01	<u>5.60<i>e</i> – 01</u> 9.23 <i>e</i> – 01	$\frac{1.04e - 01}{8.36e - 01}$	$rac{1.48e-02}{7.56e-01}$	$\frac{2.02e - 03}{6.85e - 01}$	<u>2.75e - 04</u> 6.20e - 01

Table 1: Ratio $\frac{(1/T_{j-1}(2\hat{\lambda}_2/\hat{\lambda}_1-1))^2}{(\hat{\lambda}_1/\hat{\lambda}_2)^{2(j-1)}}$ for varying subspace dimensions j and ratios $\hat{\lambda}_2/\hat{\lambda}_1$.

An orthogonal basis for \mathcal{K}_m

Problem: The matrix

$$\mathcal{K}_m(\mathcal{A},\mathbf{x}) := \left[\begin{array}{c|c} \mathbf{x} & \mathcal{A}\mathbf{x} & \cdots & \mathcal{A}^{m-1}\mathbf{x} \end{array} \right]$$

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becomes more and more ill-conditioned as m increases. (Remember vector iteration for computing largest eigenvalue.)

Solution: We have to find a well-conditioned basis of \mathcal{K}_m .

Arnoldi & Lanczos algorithms

Task: For j = 1, 2, ..., m, compute orthonormal bases $\{\mathbf{v}_1, ..., \mathbf{v}_j\}$ for the Krylov spaces

$$\mathcal{K}_j = \mathsf{span}\left\{\mathbf{x}, A\mathbf{x}, A^2\mathbf{x}, \dots, A^{j-1}\mathbf{x}
ight\}.$$

The algorithms that do this are

- Lanczos algorithm for A symmetric/Hermitian.
- Arnoldi algorithm for A nonsymmetric.

Difficulty: Because of ill-conditioning, do not want to *explicitly* form $\mathbf{x}, A\mathbf{x}, \dots, A^{j}\mathbf{x}$.

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Orthogonal basis

Arnoldi & Lanczos algorithms (cont.)

Instead of using $A^{j}\mathbf{x}$ we proceed with $A\mathbf{v}_{j}$. (Notice that $A\mathbf{v}_{i} \in \mathcal{K}_{i+1} \subset \mathcal{K}_{j}$ for all i < j.)

Orthogonalize $A\mathbf{v}_j$ against $\mathbf{v}_1, \ldots, \mathbf{v}_j$ by the Gram–Schmidt:

$$\mathbf{w}_j = A\mathbf{v}_j - \sum_{i=1}^j \mathbf{v}_i h_{ij}.$$

 \mathbf{w}_{j} points in the desired new direction (unless it is **0**). Therefore,

$$\mathbf{v}_{j+1} = \mathbf{w}_j / \|\mathbf{w}_j\|.$$

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Arnoldi algo to compute orthonormal basis of Krylov space

1: Let
$$A \in \mathbb{R}^{n \times n}$$
. This algorithm computes orthonormal basis for $\mathcal{K}^{j}(\mathbf{x})$
2: $\mathbf{v}_{1} = \mathbf{x}/||\mathbf{x}||_{2}$;
3: for $j = 1, ..., d\mathbf{o}$
4: $\mathbf{r} := A\mathbf{v}_{j}$;
5: for $i = 1, ..., j$ do {Gram-Schmidt orthogonalization}
6: $h_{ij} := \mathbf{v}_{i}^{*}\mathbf{r}, \quad \mathbf{r} := \mathbf{r} - \mathbf{v}_{i}h_{ij}$;
7: end for
8: $h_{j+1,j} := ||\mathbf{r}||$;
9: if $h_{j+1,j} = 0$ then {Found an invariant subspace}
10: return $(\mathbf{v}_{1}, ..., \mathbf{v}_{j}, H \in \mathbb{R}^{j \times j})$
11: end if
12: $\mathbf{v}_{j+1} = \mathbf{r}/h_{j+1,j}$;
13: end for
14: return $(\mathbf{v}_{1}, ..., \mathbf{v}_{j+1}, H \in \mathbb{R}^{j+1 \times j})$

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Arnoldi relation

The Arnoldi algorithm returns if $h_{m+1,m} = 0$, i.e., if it has found an invariant subspace. The vectors $\{\mathbf{v}_1, \ldots, \mathbf{v}_m\}$ then form an invariant subspace of A,

$$AV_m = V_m H_m, \qquad V_m = [\mathbf{v}_1, \dots, \mathbf{v}_m].$$

The eigenvalues of H_m are eigenvalues of A as well and the Ritz vectors are eigenvectors of A.

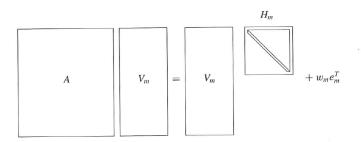
This algorithm costs j matrix-vector multiplications, $n^2/2 + O(n)$ inner products, and the same number of _axpy's.

In general, we cannot afford to store the vectors $\mathbf{v}_1, \ldots, \mathbf{v}_m$ because of limited memory space. So, we stop prematurely

Arnoldi relation (cont.)

Define $V_m := [\mathbf{v}_1, \ldots, \mathbf{v}_m]$. Then we get the Arnoldi relation

$$AV_m = V_m H_m + \mathbf{w}_m \mathbf{e}_m^T = V_{m+1} \bar{H}_m.$$



Picture from Saad: Iterative Methods for Sparse Linear Systems:

Orthogonal basis

Arnoldi relation (cont.)

Here,

$$\bar{H}_m = \begin{bmatrix} h_{11} & h_{12} & \cdots & h_{1,m} \\ h_{21} & h_{22} & \cdots & h_{2,m} \\ & h_{3,2} & \cdots & h_{3,m} \\ & & \ddots & \vdots \\ & & & & h_{m+1,m} \end{bmatrix}$$

The square matrix $H_m \in \mathbb{R}^{m \times m}$ is obtained from $\overline{H}_m \in \mathbb{R}^{(m+1) \times m}$ by deleting the last row. Notice that

$$H_m = V_m^T A V_m$$

If A is symmetric $\implies H_m \equiv T_m$ is symmetric and thus tridiagonal! The Lanczos relation is $AV_m = V_m T_m + \mathbf{w}_m \mathbf{e}_m^T = V_{m+1} \overline{T}_m$.

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