Submitted to *Axioms*. Pages 1 - 44.

OPEN ACCESS

Article

Complexity L^0-Penalized M-Estimation: Consistency in More Dimensions

Laurent Demaret [1,⋆], Felix Friedrich [2], Volkmar Liebscher [3] and Gerhard Winkler [4]

[1] IBB, HMGU Munich, Ingolstädter Landstr. 1, D-85764 Neuherberg, Germany

[2] ETH Zentrum RZ H9, Zürich, Switzerland; partially supported by HMGU Munich, Germany

[3] Ernst-Moritz-Arndt-Universität Greifswald, Germany

[4] Ludwig-Maximilians Universität München, Germany

* Author to whom correspondence should be addressed; laurent.demaret@helmholtz-muenchen.de, Tel: 00 49 89 31 87 24 36, Fax: 00 49 89 31 87 33 69.

Version February 13, 2013 submitted to Axioms. *Typeset by LaTeX using class file mdpi.cls*

Abstract: We study the asymptotics in L^2 for complexity penalized least squares regression for the discrete approximation of finite-dimensional signals on continuous domains - e.g. images - by piecewise smooth functions. We introduce a fairly general setting which comprises most of the presently popular partitions of signal- or image- domains like interval-, wedgelet- or related partitions, as well as Delaunay triangulations. Then we prove consistency and derive convergence rates. Finally, we illustrate by way of relevant examples that the abstract results are useful for many applications.

Keywords: keyword; keyword; keyword

1. Introduction

We are going to study consistency of special complexity penalized Least Squares estimators for noisy observations of finite-dimensional signals on multi-dimensional domains, in particular of images. The estimators discussed in the present paper are based on partitioning combined with piecewise smooth approximation. In this framework, consistency is proved and convergence rates are derived in L^2. Finally, the abstract results are applied to a couple of relevant examples, including popular methods like interval-, wedgelet- or related partitions, as well as Delaunay triangulations. Fig. 1 illustrates a typical wedgelet representation of a noisy image.

Consistency is a strong indication that an estimation procedure is meaningful. Moreover, it allows for structural insight since a sequence of discrete estimation procedures is embedded into a common continuous setting and the quantitative behaviour of estimators can be compared. It is frequently used as a substitute or approximation for missing or vague knowledge in the real finite sample situation. Plainly, one must be aware of various shortcomings and should not rely on asymptotics in case of small sample size. Nevertheless, consistency is a broadly accepted justification of statistical methods. Convergence rates are of particular importance, since they indicate the quality of discrete estimates or approximations and allow for comparison of different methods.

Observations or data will be governed by a simple regression model with additive white noise: Let $S^n = \{1, \dots, n\}^d$ be a finite discrete signal domain, interpreted as the discretization of the continuous domain $S^\infty = [0, 1)^d$. Data $y = (y_s)_{s \in S^n}$ are available for the discrete domains at all levels n and generated by the model

$$Y_s^n = \bar{f}_s^n + \xi_s^n, \ \ n \in \mathbb{N}, \ \ s \in S^n, \tag{1}$$

where $(\bar{f}_s^n)_{s \in S^n}$ is a discretisation of an original or 'true' signal f on S^∞ and $(\xi_s^n)_{s \in S^n}$ is white (sub-)Gaussian noise.

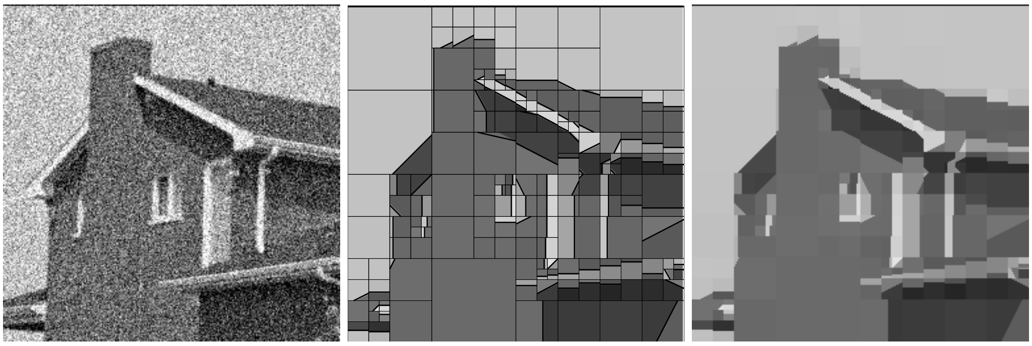

Figure 1. A noisy image (left) and (right) a fairly rough wedgelet representation for $n = 256$. The (middle) picture also shows the boundaries of the smoothness regions.

The present approach is based on a partitioning of the discrete signal domain into regions on each of which a smooth approximation of noisy data is performed. The choice of a particular partition is obtained by a complexity penalized least squares estimation, dependent on the data. Between the regions, sharp breaks of intensity may happen, which allows for edge-preserving piecewise smoothing. In one dimension, a natural way to model jumps in signals is to consider piecewise regular functions. This leads naturally to representations based on partitions consisting of intervals. The number of intervals on a discrete line of length n is of polynomial order n^2.

In more dimensions, however, the definition of elementary fragments is much more involved. For example, in a discrete square of side-length n, the number of all subregions is of the exponential order 2^{n^2}. When dealing with images, one of the difficulties consists in constructing reduced sets of fragments which, at the same time, take into account the geometry of images and lead to computationally feasible algorithms for the computation of estimators.

The estimators adopted here are minimal points of complexity penalized least squares functionals: if $y = (y_s)_{s\in S^n}$ is a sample and $x = (x_s)_{s\in S^n}$ a tentative representation of y, the functional

$$H^n(x,y) = \gamma|\mathscr{P}(x)| + \sum_{s\in S^n}(y_s - x_s)^2 \tag{2}$$

has to be minimized in x given y; the penalty $\gamma|\mathscr{P}(x)|$ is the number of subdomains into which the entire domain is divided and on which x is smooth in a sense to be made precise by the choice of suitable function spaces (see Sections 2.1 and 5); γ is a tuning parameter. This automatically results in a sparse representation of the function. Due to the non-convexity of L^0-type penalty one has to solve hard optimization problems in general.

These are not computationally feasible, if all possible partitions of the signal domain are admitted. A most popular attempt to circumvent this nuisance is simulated annealing, see for instance the seminal paper S. GEMAN and D. GEMAN [23]. This paper had a considerable impact on imaging; the authors transferred models from statistical physics to image analysis as prior distributions in the framework of Bayesian statistics. This approach was intimately connected with Markov Chain Monte Carlo Methods like Metropolis Sampling and Simulated Annealing, cf. G. WINKLER [36].

On the other hand, transferring spatial complexity to time complexity like in such metaheuristics, does not remove the basic problem; it rather transforms it. Such algorithms are not guaranteed to find the optimum or even a satisfactory near-optimal solution, cf. G. WINKLER [36], Section 6.2. All metaheuristics will eventually encounter problems on which they perform poorly.

Moreover, if the number of partitions grows at least exponentially, it is difficult to derive useful uniform bounds on the projections of noise onto the subspaces induced by the partitions. Reducing the search space drastically allows to design exact and fast algorithms. Such a reduction basically amounts to restrictions on admissible partitions of the signal domain. There are various suggestions, some of them mentioned initially.

In one dimension, regression onto piecewise constant functions was proposed by the legendary J.W. TUKEY [34] who called respective representations regressograms. The functional (2) is by some (including the authors) referred to as the *Potts functional*. It was introduced in R.B. POTTS [33] as a generalization of the well-known Ising model, E. ISING [25], from statistical physics from two to more spins. It was suggested by W. LENZ [29] and penalizes the length of contours between regions of constant spins. In fact, in one dimension a partition $\mathscr{P}$ into say k intervals on which the signal is constant admits $k-1$ jumps and therefore has contour-length $k-1$.

The one-dimensional Potts model for signals was studied in detail in a series of theses and articles, see F. FRIEDRICH [20], F. FRIEDRICH et al. [22], A. KEMPE [27], V. LIEBSCHER and G. WINKLER [30], G. WINKLER et al. [37], G. WINKLER and V. LIEBSCHER [38], G. WINKLER et al. [39], O. WITTICH et al. [40]. Consistency was first adressed in A. KEMPE [27] and later on exhaustively treated in L. BOYSEN et al. [3] and L. BOYSEN et al. [4]. Partitions consist there of intervals. Our study of the multi-dimensional case started with the thesis F. FRIEDRICH [20], see also F. FRIEDRICH et al. [21].

In two or more dimensions, the model (2) differs substantially from the classical Potts model. The latter penalizes the *length of contours* - locations of intensity breaks - whereas (2) penalizes the *number of regions*. This allows for instance to perform well on filamentous structures, albeit they have long borders compared to their area.

Let us give an informal introduction into the setting. The aim is to estimate a function f on the d-dimensional unit cube $S^\infty = [0,1)^d$ from discrete data. To this end, S^∞ and f are discretized to cubic grids $S^n = \{1, \ldots, n\}^d$, $n \in \mathbb{N}$, and functions $\bar{f}^n$ on S^n. On each stage n, data y_s^n, $s \in S^n$, is available, i.e. noisy observations of the $\bar{f}_s^n$. We will prove L^2-convergence of complexity penalized least squares estimators $\hat{f}^n(y)$, corresponding to minimal points of (2) (Section 2.2) for the $\bar{f}^n$ and derive convergence rates, first in the general setting. We are faced with three kinds of error: the error caused by noise, the approximation and the discretization error. Noise is essentially controlled regardless of the specific form of f. For the approximation and the discretisation error special assumptions on the function classes in question are needed.

Because of the approximation error term, there are deep connections to approximation theory. In particular, when dealing with piecewise regular images, non linear approximation rates obtained by wavelet shrinkage methods are known to be suboptimal, as discussed in R. KOROSTELEV and TSYBAKOV [28] or D. DONOHO [16]. In the last decade, the challenging problem to improve upon wavelets has been addressed in very different directions.

The search for a good paradigm for detecting and representing curvilinear discontinuities of bivariate functions remains a fundamental issue in image analysis. Ideally, an efficient representation should use atomic decompositions which are local in space (like wavelets), but also possess appropriate directional properties (unlike wavelets). One of the most prominent examples is given by curvelet representations, which are based on multiscale directional filtering combined with anisotropic scaling. E. CANDÈS and D. DONOHO [8] proved that thresholding of curvelet coefficients provides estimators which yield the minimax convergence rate up to a logarithmic factor for piecewise $\mathscr{C}^2$ functions with $\mathscr{C}^2$ boundaries. Another interesting representation is given by bandelets as proposed in E. LE PENNEC and S. MALLAT [31]. Bandelets are based on optimal local warping in the image domain relatively to the geometrical flow and C. DOSSAL et al. [17] proved also optimality of the minimax convergence rates of their bandelet-based estimator, for a larger class of functions including piecewise $\mathscr{C}^\alpha$ functions with $\mathscr{C}^\alpha$ boundaries.

In Section 5 we apply the abstract framework proposed in Section 4 to bidimensional examples that rely on explicit geometrical constructions: in particular, the corresponding approaches are aimed at avoiding the pseudo-Gibbs artifacts produced by the above methods.

Wedgelet partitions were introduced by D. DONOHO [16] and belong to the class of shape-preserving image segmentation methods. The decompositions are based on local polynomial approximation on some adaptively selected leaves of a quadtree structure. The use of a suitable data structure allowed for the development of fast algorithms for wedgelet decomposition, see F. FRIEDRICH et al. [21].

An alternative is provided by anisotropic Delaunay triangulations, which have been proposed in the context of image compression in L. DEMARET et al. [10]. The flexible design of the representing system allows for a particularly fine selection of triangles fitting the anisotropic geometrical features of images. In contrast to curvelets, such representations preserve the advantage of wavelets and are still able to approximate point singularities optimally, see L. DEMARET and A. ISKE [13].

Both wedgelet representations and anisotropic Delaunay triangulations lead to optimal non linear approximation rates for some classes of piecewise smooth functions. In the present paper, we prove optimality also for the convergence rates of the estimators. More precisely, we prove strong consistency rates of

$$O(\varepsilon_n^{2\alpha/(\alpha+1)}\log(\varepsilon_n)), \quad \varepsilon_n = \sigma^2/n^d,$$

where σ^2 is the variance of noise and α is a parameter controlling piecewise regularity. Such rates are known to be optimal up to the logarithmic factor.

L. BIRGÉ and P. MASSART [2] showed recently that, in a similar setting, optimal rates without the $\log$ factor may be achieved with penalties slightly different from those in (2), and not merely proportional to the number of pieces. In the present work, we explicitly restrict our attention to the classical penalty given by the number of pieces as in (2), noting that this corresponds to the *sparse ansatz* which is currently popular in the signal community. We refer to M. ELAD [19] for a comprehensive review on sparsity. The generalization of the proofs in this paper is straightforward but would be rather technical and thus might obscure the main ideas.

We address first noise and its projections to the approximation spaces, see Section 3. In Section 4, we derive convergence rates in the general context. Finally, in Section 5, we illustrate the abstract results by specific applications. Dimension 1 is included, thus generalizing the results from L. BOYSEN et al. [3] to piecewise polynomial regression and piecewise Sobolev classes. Our two-dimensional examples, wedgelets and Delaunay triangulations, both rely on a geometric and edge-preserving representation. Our main motivation are the optimal approximation properties of these methods, the key feature to apply the previous framework being an appropriate discretization of these schemes.

2. The Setting

In this section we introduce the formal framework for piecewise smooth representations, the regression model for data, and the estimation procedure.

2.1. Regression and Segmentations

Image domains will generically be denoted by S. We choose $S^\infty = [0,1)^d$, $d \in \mathbb{N}$, as the continuous and $S^n = \{1, \dots, n\}^d$ as the generic discrete image domain. Let $f \in L^2(S^\infty)$ represent the 'true' image which has to be reconstructed from noisy discrete data. For the latter, we adopt a simple linear regression model of the form

$$Y_s^n = \bar{f}_s^n + \xi_s^n, \;\; n \in \mathbb{N}, \;\; s \in S^n. \tag{3}$$

The noise variables ξ_s^n in the regression model are random variables on a common probability space $(\Omega, \mathscr{F}, \mathbb{P})$. $\bar{f}^n = (\bar{f}^n{}_s)_{s \in S^n}$ is a discretisation of f. To be definite, divide S^∞ into n^d semi-open cubes

$$I^n_{i_1,\ldots,i_d} = \prod_{1 \le j \le d} [(i_j - 1)/n, i_j/n),\ 1 \le i_j \le n,$$

of volume $1/n^d$ and for $g \in L^2(S^\infty)$ take local means

$$\bar{g}^n_s = n^d \int_{I_s} g(u)\, du,\ \ s \in S^n.$$

This specifies maps δ^n from $L^2(S^\infty)$ to $\mathbb{R}^{S^n}$ by

$$\delta^n g = (\bar{g}^n_s)_{s \in S^n}. \tag{4}$$

Conversely, embeddings of $\mathbb{R}^{S^n}$ into $L^2(S^\infty)$ are defined by

$$z = (z_s)_{s \in S^n} \longmapsto \iota^n z = \sum_{s \in S^n} z_s \boldsymbol{1}_{I_s}. \tag{5}$$

As an aid to memory, keep the following chain of maps in mind:

$$L^2(S^\infty) \xrightarrow{\delta^n} \mathbb{R}^{S^n} \xrightarrow{\iota^n} L^2(S^\infty).$$

In absence of noise, f is approximated by the functions $\iota^n \bar{f}^n = \iota^n \delta^n f$ in any precision. Thus, the main task will be to control noise. In fact, the function $\iota^n \delta^n f = \iota^n \bar{f}^n$ is the conditional expectation of f w.r.t. the (σ)-algebra $\mathscr{A}^n$ generated by the cubes I^n_s and convergence can be seen by a martingale argument.

We are dealing with estimates of f or rather of $\bar{f}^n$ on each level n. An image domain S will be partitioned by the method into sets, on which the future representations are members of initially chosen spaces of smooth functions. To keep control, we choose a class $\mathscr{R} \subset 2^S$ of *admissible fragments* and later on, these will be rectangles, wedges or triangles. A subset $\mathscr{P} \subset 2^S$ is a *partition* if (a) the elements in $\mathscr{P}$ are mutually disjoint, and (b) S is the union of all $P \in \mathscr{P}$. In the following, we choose a subset $\mathfrak{P}$ of the set of all partitions $\mathscr{P} \subset \mathscr{R}$. We call elements of $\mathfrak{P}$ *admissible partitions*.

For each fragment $P \in \mathscr{R}$, we choose a finite dimensional linear space $\mathscr{F}_P$ of real functions on S which vanish off P. Examples are spaces of constant functions or polynomials of higher degree. This space is determined by the maximal local smoothness of f. If $\mathscr{P} \in \mathfrak{P}$ and $f_{\mathscr{P}} = (f_P)_{P \in \mathscr{P}}$ is a family of such functions, we also denote by $f_{\mathscr{P}}$ the function defined on all of S and whose restriction to P is equal to f_P for each $P \in \mathscr{P}$. The pair $(\mathscr{P}, f_{\mathscr{P}})$ is a *segmentation* and each element (P, f_P) is a *segment*.

For each partition $\mathscr{P}$, define the linear space $\mathscr{F}_{\mathscr{P}} = \mathrm{span}\{\mathscr{F}_P : P \in \mathscr{P}\}$. A family of segmentations is called a *segmentation class*. In particular, let

$$\mathfrak{S}(\mathfrak{P}, \mathfrak{F}) := \{(\mathscr{P}, f) : \mathcal{P} \in \mathfrak{P}, f \in \mathscr{F}_{\mathscr{P}}\}$$

with partitions in $\mathfrak{P}$ and functions in $\mathfrak{F} = \{\mathscr{F}_{\mathscr{P}} : \mathscr{P} \in \mathfrak{P}\}$.

2.2. Complexity Penalized Least Squares Estimation

We want to produce appropriate discrete representations or estimates of the underlying function f on the basis of random data Y from the regression model (3). We are watching out for a segmentation which is in proper balance between fidelity to data and complexity.

We decide in advance on a class $\mathfrak{S}$ of (admissible) segmentations which should contain the desired representations. The segmentations, given data Y^n, are scored by the functional

$$H_\gamma^n : \mathfrak{S}^n \times \mathbb{R}^{S^n} \longrightarrow \mathbb{R},\ H_\gamma^n((\mathscr{P}, f_{\mathscr{P}}), Y^n) = \gamma|\mathscr{P}| + \|f_{\mathscr{P}} - Y^n\|^2, \qquad (6)$$

with $\gamma \geq 0$ and $|\mathscr{P}|$ the cardinality of $\mathscr{P}$. The symbol $\|\cdot\|$ denotes the ℓ^2-norm on $\mathbb{R}^{S^n}$. The last term measures fidelity to data. The other term is a rough measure of overall smoothness. As estimators for f given data Y we choose minimisers $(\hat{\mathscr{P}}^n, \hat{f}^n)$ of (6). Note that both $\hat{\mathscr{P}}^n$ and $\hat{f}^n$ are random since Y^n is random.

The definition makes sense since minimal points of (6) do always exist. This can easily verified by the *reduction principle*, which relies on the decomposition

$$\min_{\mathscr{P} \in \mathfrak{P}^n, f_{\mathscr{P}} \in \mathscr{F}_{\mathscr{P}}} H_\gamma^n((\mathscr{P}, f_{\mathscr{P}}), Y) = \min_{\mathscr{P} \in \mathfrak{P}^n} \left(\gamma|\mathscr{P}| + \min_{f_{\mathscr{P}} \in \mathscr{F}_{\mathscr{P}}} \|f_{\mathscr{P}} - Y\|^2 \right).$$

Given $\mathscr{P}$, the inner minimisation problem has as unique solution the orthogonal projection $\hat{f}_{\mathscr{P}}^n$ of Y to $\mathscr{F}_{\mathscr{P}}$. The outer minimisation problem is finite and hence a minimum of (6) exists. Let us pick one of the minimal points $\hat{f}^n$.

3. Noise and its Projections

For consistency, resolutions at infinitely many levels are considered simultaneously. Frequently, segmentations are not defined for all $n \in \mathbb{N}$ but only for a cofinal subset of $\mathbb{N}$. Typical examples are all dyadic quad-tree partitions or dyadic wedgelet segmentations where only indices of the form $n = 2^p$ appear. Therefore we adopt the following convention:

The symbol $\mathbb{M}$ denotes any infinite subset of $\mathbb{N}$ endowed with the natural order $\leq$.

$(\mathbb{M}, \leq)$ is a totally ordered set and we may consider nets $(x_n)_{n\in\mathbb{M}}$. For example $x_n \to x$, $n \in \mathbb{M}$, means that x_n convergences to x along $\mathbb{M}$. We deal similarly with notions like $\limsup$ etc. Plainly, we might resort to subsequences instead but this would cause a change of indices which is notationally inconvenient.

3.1. Sub-Gaussian Noise and a Tail Estimate

We introduce now the main hypotheses on noise accompanied by a brief discussion. The core of the arguments in later sections is the tail estimate (8) below.

As Theorem 2 will show, the appropriate framework are *sub-Gaussian* random variables. A random variable ξ enjoys this property if one of the following conditions is fulfilled:

Theorem 1 *The following two conditions on a random variable ξ are equivalent:*
(a) There is $a \in \mathbb{R}$ such that

$$\mathbb{E}(\exp(t\xi)) \leq \exp(a^2t^2/2) \text{ for } t > 0 \tag{7}$$

(b) ξ is centred and majorized in distribution *by some centred Gaussian variable η, i.e.*

$$\textit{there is } c_0 \geq 0 \textit{ such that } \mathbb{P}(|\xi| \geq c) \leq \mathbb{P}(|\eta| \geq c) \textit{ for all } c > c_0.$$

This and most other facts about sub-Gaussian variables quoted in this paper are verified in the first few sections of the monograph V.V. BULDYGIN and YU.V. KOZACHENKO [6]; one may also consult V.V. PETROV [32], Section III.§4.

The definition in *(a)* was given in the celebrated paper Y.S. CHOW [9] which uses the term *generalized Gaussian variables*. The closely related concept of semi-Gaussian variables - which requires symmetry of ξ - seems to go back to J.P. KAHANE [26].

The class of all sub-Gaussian random variables living on a common probability space $(\Omega, \mathscr{A}, \mathbb{P})$ is denoted by $\mathrm{Sub}(\Omega)$. The *sub-Gaussian standard* is the number

$$\tau(\eta) = \inf\{a \geq 0 : a \text{ is feasible in } (7)\}.$$

The infimum is attained and hence is a minimum. $\mathrm{Sub}(\Omega)$ is a linear space, τ is a norm on $\mathrm{Sub}(\Omega)$ if variables differing on a null-set only are identified. $(\mathrm{Sub}(\Omega), \tau)$ is a Banach space. It is important to note that $\mathrm{Sub}(\Omega)$ is strictly contained in all spaces $L_0^p(\Omega)$, $p \geq 1$, the spaces of all centred variables with finite p^{th} order absolute moments.

Remark 1 *The most prominent sub-Gaussians are centred Gaussian variables η with standard deviation σ and $\tau(\eta) = \sigma$. For them inequality (7) is an equality with $a = \sigma$. The specific characteristic of sub-Gaussian variables are tails lighter than those of Gaussians, as expressed in* (b) *of Theorem 1.*

The following theorem is essential in the present context.

Theorem 2 *For each $n \in \mathbb{M}$, suppose that the variables ξ_s^n, $s \in S^n$, are independent. Then*

(a) Suppose that there is a real number $\beta > 0$ such that for each $n \in \mathbb{M}$ and real numbers μ_s, $s \in S^n$, and each $c \in \mathbb{R}_+$, the estimate

$$\mathbb{P}\left(\left|\sum_{s\in S_n} \mu_s \xi_s^n\right| \geq c\right) \leq 2 \cdot \exp\left(-\frac{c^2}{\beta \sum_{s\in S_n} \mu_s^2}\right) \tag{8}$$

holds. Then all variables ξ_s^n are sub-Gaussian with a common scale factor β.

(b) Let all variables ξ_s^n be sub-Gaussian. Suppose further that

$$\beta = 2 \cdot \sup\{\tau^2(\xi_s^n) : n \in \mathbb{M},\ s \in S^n\} < \infty. \tag{9}$$

Then (a) is fulfilled with this factor β.

This is probably folklore and we skip the proof. A detailed proof can be found in the extended version L. DEMARET et al. [11].

Remark 2 For white Gaussian noise one has $\tau(\xi_s^n) = \sigma$ and hence $\beta = 2\sigma^2$.

3.2. Noise Projections

In this section, we quantify projections of noise. Choose for each $n \in \mathbb{M}$ a class $\mathscr{R}^n \subset 2^{S^n}$ of admissible segments over S^n and a set $\mathfrak{P}^n$ of admissible partitions. As previously, for each $P \in \mathscr{R}^n$, a linear function space $\mathscr{F}_P$ is given. We shall denote orthogonal L^2-projections onto the linear spaces $\mathscr{F}_{\mathscr{P}} = \operatorname{span}\{\mathscr{F}_P : P \in \mathscr{P}\}$ by $\pi_{\mathscr{P}}$.

The following result provides L^2-estimates for the projections of noise to these spaces, as there are more and more admissible segments.

Proposition 1 *Suppose that* $\dim \mathscr{F}_P \le D$ *for all* $n \in \mathbb{M}$ *and each* $P \in \mathscr{R}^n$. *Assume in addition that there is a number* $M > 0$ *such that for some* $\kappa > 0$

$$|\mathscr{R}^n| \ge M \cdot n^\kappa \;\; \textit{eventually}.$$

Then for each $C > (1/\kappa + 1)\beta D$ *and for almost all* $\omega \in \Omega$

$$\|\pi_{\mathscr{P}^n} \xi^n(\omega)\|^2 \le C|\mathscr{P}^n| \ln(|\mathscr{R}^n|) \quad \textit{for eventually all } n \in \mathbb{M} \textit{ and each } \mathscr{P}^n \in \mathfrak{P}^n.$$

This will be proven at a more abstract level. No structure of the finite sets S^n is required. Nevertheless, we adopt all definitions from Section 1 *mutatis mutandis*. All Euclidean spaces $\mathbb{R}^k$ will be endowed with their natural inner products $\langle \cdot, \cdot \rangle$ and respective norms. Projections onto linear subspaces $\mathscr{H}$ will be denoted by $\pi_{\mathscr{H}}$.

Theorem 3 *Suppose that the noise variables* ξ_s^n *fulfill (8) accordingly. Consider finite nonempty collections* $\mathfrak{H}^n$ *of linear subspaces in* $\mathbb{R}^{S^n}$ *and assume that the dimensions of all subspaces* $\mathscr{H} \in \mathfrak{H}^n$, $n \in \mathbb{M}$, *are uniformly bounded by some number* $D \in \mathbb{N}$. *Assume in addition that there is a number* $M > 0$ *such that for some* $\kappa > 0$

$$|\mathfrak{H}^n| \ge M \cdot n^\kappa \;\; \textit{eventually}.$$

Then for each $C > (1/\kappa + 1)\beta D$ *and for almost all* $\omega \in \Omega$

$$\|\pi_{\mathscr{H}} \xi^n(\omega)\|^2 \le C \ln(|\mathfrak{H}^n|) \quad \textit{for eventually all } n \in \mathbb{M}, \textit{ and each } \mathscr{H} \in \mathfrak{H}^n .$$

Note that $\|\cdot\|$ is Euclidean norm in the spaces $\mathbb{R}^{S_n}$, since each $\xi^n(\omega)$ is simply a vector. The assumption in the theorem can be reformulated as $|\mathfrak{H}^n|^{-1} = O(n^{-\kappa})|$.

Proof. Choose $n \in \mathbb{M}$ and $\mathscr{H} \in \mathfrak{H}^n$ with $\dim \mathscr{H} = d_n$. Let e_i, $1 \le i \le d_n$ be some orthonormal basis of $\mathscr{H}$. Observe that for any real number $c > 0$,

$$\sum_{i=1}^{d_n} |\langle \xi^n(\omega), e_i \rangle|^2 > c^2 \ln |\mathfrak{H}^n|$$

implies that

$$|\langle \xi^n(\omega), e_i \rangle|^2 > \frac{c^2}{d_n} \ln |\mathfrak{H}^n| \text{ for at least one } i = 1, \ldots, d_n.$$

254 We derive a series of inequalities:

$$\begin{aligned} & \mathbb{P}\left(\|\pi_{\mathscr{H}}\xi^n\|^2 > c^2 \ln |\mathfrak{H}^n|\right) = \mathbb{P}\left(\sum_{i=1}^{d_n} |\langle \xi^n, e_i \rangle|^2 > c^2 \ln |\mathfrak{H}^n|\right) \\ \le \; & \mathbb{P}\left(\bigcup_{i=1}^{d_n} \{|\langle \xi^n, e_i \rangle|^2 > \frac{c^2}{d_n} \ln |\mathfrak{H}^n|\}\right) \le \sum_{i=1}^{d_n} \mathbb{P}\left(|\langle \xi^n, e_i \rangle|^2 > \frac{c^2}{d_n} \ln |\mathfrak{H}^n|\right) \\ = \; & \sum_{i=1}^{d_n} \mathbb{P}\left(\left|\sum_{s \in S^n} \xi^n_s e_{i,s}\right| > c\left(\ln |\mathfrak{H}^n|/d_n\right)^{1/2}\right), \end{aligned}$$

where the first inequality holds because of the introductory implication. By (8) we may continue with

$$\le 2 \cdot d_n \exp\left(\frac{-c^2 \ln |\mathfrak{H}^n|}{\beta d_n \sum_{s \in S^n} e_{i,s}^2}\right) \le 2 \cdot D \cdot |\mathfrak{H}^n|^{\frac{-c^2}{\beta D}}.$$

255 Therefore

$$\begin{aligned} & \sum_{n \in \mathbb{M}, \mathscr{H} \in \mathfrak{H}^n} \mathbb{P}\left(\|\pi_{\mathscr{H}}\xi^n\|^2 > c^2 \ln |\mathfrak{H}^n|\right) \le 2D \sum_{n \in \mathbb{M}, \mathscr{H} \in \mathfrak{H}^n} |\mathfrak{H}^n|^{\frac{-c^2}{\beta D}} \le 2D \sum_{n \in \mathbb{M}} |\mathfrak{H}^n| |\mathfrak{H}^n|^{\frac{-c^2}{\beta D}} \\ \le \; & 2D \sum_{n \in \mathbb{M}} \left(\frac{1}{M} \cdot n^{-\kappa}\right)^{\frac{c^2}{\beta D} - 1} = 2D \cdot M^{1 - c^2/(\beta D)} \sum_{n \in \mathbb{M}} n^{-\kappa(\frac{c^2}{\beta D} - 1)}. \end{aligned}$$

For $C = c^2 > (1/\kappa + 1)\beta D$ the negative exponent becomes larger than 1 and the sum becomes finite. Enumeration of each $\mathfrak{H}^n$ and subsequent concatenation yields a sequence of events. The Borel-Cantelli lemma yields

$$\mathbb{P}(\|\pi_{\mathscr{H}}\xi^n\| > C \ln |\mathfrak{H}_n| \quad \text{for finitely many } (n, \mathscr{H}) \text{ with } \mathscr{H} \in \mathfrak{H}^n) = 1.$$

This implies the assertion. □

Now let us prove the desired result.

Proof of Proposition 1. We apply Theorem 3 to the collections $\mathfrak{H}^n = \{\mathscr{F}^n_R : R \in \mathscr{R}^n\}$. Then $|\mathfrak{H}^n| = |\mathscr{R}^n|$. Since for each $\mathscr{P}^n \in \mathfrak{P}^n$ the spaces $\mathscr{F}^n_P$, $P \in \mathscr{P}^n$, are mutually orthogonal, one has for $z \in \mathbb{R}^{S^n}$ that

$$\|\pi_{\mathscr{P}^n} z\|^2 = \sum_{P \in \mathscr{P}^n} \|\pi_{\mathscr{F}^n_P} z\|^2$$

and hence for almost all $\omega \in \Omega$

$$\|\pi_{\mathscr{P}^n} \xi^n(\omega)\|^2 \leq \sum_{P \in \mathscr{P}^n} C \cdot \ln |\mathscr{R}^n| = C \cdot |\mathscr{P}^n| \cdot \ln |\mathscr{R}^n| \text{ for eventually all } n \in \mathbb{M}.$$

This completes the proof. □

Let us finally illustrate the above concept in the classical case of Gaussian white noise.

Remark 3 Continuing from Remark 2, we illustrate the behaviour of the lower bound for the constant C in Proposition 1 and Theorem 3 in the case of white gaussian noise and polynomially growing number of fragments, i.e. $|\mathscr{R}^n|$ is asymptotically equivalent to n^κ. In this case the estimate for the norm of noise projections takes the form

$$\|\pi_{\mathscr{P}^n} \xi^n(\omega)\|^2 \leq \left(\frac{1}{\kappa} + 1\right) \kappa 2\sigma^2 D |\mathscr{P}^n| \ln n = (1+\kappa) 2\sigma^2 D |\mathscr{P}^n| \ln n,$$
for almost each ω eventually.

This underlines the dependency between the noise projections, the number of fragments, the noise variance, the dimension of the regression spaces and the size of the partitions.

3.3. Discrete and Continuous Functionals

We want to approximate functions f on the continuous domain $S^\infty = [0,1)^d$ by estimates on discrete finite grids S^n. The connections between the two settings are provided by the maps ι^n and δ^n, introduced in (4) and (5). Note first that

$$\langle \iota^n x, \iota^n y \rangle = \langle x, y \rangle / |S^n| \text{ and } \|\iota^n x\|^2 = \|x\|^2 / |S^n| \quad \text{for } x, y \in \mathbb{R}^{S^n}, \qquad (10)$$

where the inner product and norm on the respective left hand sides are those on $L^2(S^\infty)$ and on the right hand sides one has the Euclidean inner product and norm. Furthermore, one needs appropriate versions of the functionals (6). Let now $\mathfrak{S}^n$ be segmentation classes on the domains S^n and $\mathfrak{S} \supset \iota^n \mathfrak{S}^n$ a segmentation class on S^∞. Set

$$\begin{aligned} H_\gamma^n : \mathbb{R}^{S^n} \times \mathfrak{S}^n,\ \ H_\gamma^n(z, (\mathscr{P}^n, g_{\mathscr{P}^n}^n)) &= \gamma|\mathscr{P}^n| + \|z - g_{\mathscr{P}^n}\|^2/|S^n| \\ \tilde{H}_\gamma^n : L^2(S^\infty) \times \mathfrak{S},\ \ \tilde{H}_\gamma^n(f, (\mathscr{P}, g_{\mathscr{P}})) &= \begin{cases} \gamma|\mathscr{P}| + \|f - g_{\mathscr{P}}\|^2 & \text{if } (\mathscr{P}, g_{\mathscr{P}}) \in \iota^n \mathfrak{S}^n, \\ \infty & \text{otherwise.} \end{cases} \end{aligned}$$

The two functionals are compatible.

Proposition 2 *Let $n \in \mathbb{M}$ and $(\mathscr{P}^n, g_{\mathscr{P}^n}) \in \mathfrak{S}^n$ and $z^n \in \mathbb{R}^{S^n}$. Then*

$$H_\gamma^n(z^n, (\mathscr{P}^n, g_{\mathscr{P}^n)}^n) = \tilde{H}_\gamma^n(\iota^n z^n, \iota^n(\mathscr{P}^n, g_{\mathscr{P}^n}^n)).$$

If, moreover, $f \in L^2(S^\infty)$ then

$$(\mathscr{P}^n, g_{\mathscr{P}^n}^n) \in \operatorname{argmin} H_\gamma^n(\delta^n f, \cdot) \textit{ if and only if } \iota^n(\mathscr{P}^n, g_{\mathscr{P}^n}^n) \in \operatorname{argmin} \tilde{H}_\gamma^n(f, \cdot)$$

Proof. The identity is an immediate consequence of (10). Hence let us turn to the equivalence of minimal points. The key is a suitable decomposition of the functional $\tilde{H}_\gamma^n(f, \cdot)$. The map $\iota^n \delta^n$ is the orthogonal projection of $L^2(S^\infty)$ onto the linear space $\mathscr{H}^n = \text{span}\{\mathbf{1}_{I_{ij}:1 \le i,j \le n}\}$, and for any $(\mathscr{P}, h) \in \iota^n \mathfrak{S}^n$ the function h is in $\mathscr{H}^n$. Hence

$$\|f - h\|^2 + \gamma|\mathscr{P}| = \|f - \iota^n \delta^n f\|^2 + \|\iota^n \delta^n f - h\|^2 + \gamma|\mathscr{P}|.$$

The quantity $\|f - \iota^n \delta^n f\|^2$ does not depend on $(\mathscr{P}, h)$. Therefore a pair $(\mathscr{P}, h)$ minimises

$$\|f - \iota^n \delta^n f\|^2 + \|\iota^n \delta^n f - h\|^2 + \gamma|\mathscr{P}|$$

if and only if it minimises

$$\|\iota^n \delta^n f - h\|^2 + \gamma|\mathscr{P}| = \tilde{H}_\gamma^n(\iota^n \delta^n f, \iota^n(\mathscr{P}, h)).$$

Setting $z^n = \delta^n f$ in (2), this completes the proof. □

3.4. Upper Bound for Projective Segmentation Classes

We compute an upper bound for the estimation error in a special setting: Choose in advance a finite dimensional linear subspace $\mathscr{G}$ of $L^2(S^\infty)$. Discretization induces linear spaces $\delta^n\mathscr{G} = \{\delta^n f : f \in \mathscr{G}\}$ and $\mathscr{G}_P^n = \{\boldsymbol{1}_P \cdot g : g \in \delta^n\mathscr{G}\}$, for any $P \subset S^n$, of functions on S^n. Let further for each $n \in \mathbb{M}$, a set $\mathscr{R}^n$ of admissible fragments and a family $\mathfrak{P}^n$ of partitions with fragments in $\mathscr{R}^n$ be given. Set $\mathfrak{G}^n := \{\mathscr{G}_{\mathscr{P}} : \mathscr{P} \in \mathfrak{P}^n\}$. The induced segmentation class

$$\mathfrak{S}^n(\mathfrak{P}^n, \mathfrak{G}^n) = \{(\mathfrak{P}^n, f) : \mathscr{P} \in \mathfrak{P}^n, f \in \mathscr{G}_{\mathscr{P}}\}$$

will be called *projective ($\mathscr{G}$-) segmentation class* at stage n.

The following inequality is at the heart of later arguments since it controls the distance between the discrete M-estimates and the 'true' signal.

Lemma 1 *Let for $n \in \mathbb{M}$ a $\mathscr{G}$-projective segmentation class $\mathfrak{S}^n$ over S^n be given and choose a signal $f \in L^2(S^\infty)$ and a vector $\xi^n \in \mathbb{R}^{S^n}$. Let further*

$$(\hat{\mathscr{P}}^n, \hat{f}^n) \in \operatorname*{argmin}_{(\mathscr{Q},h)\in\mathfrak{S}^n} H_\gamma^n(\delta^n f + \xi^n, (\mathscr{Q}, h))$$

and $(\mathscr{Q}, h) \in \mathfrak{S}^n$. Then

$$\|\iota^n \hat{f}^n - f\|^2 \leq 2\gamma(|\mathscr{Q}| - |\hat{\mathscr{P}}^n|) + 3\|\iota^n h - f\|^2 + \frac{16}{n^d}\left(\|\pi_{\hat{\mathscr{P}}^n}\xi^n\|^2 + \|\pi_{\mathscr{Q}}\xi^n\|^2\right). \quad (11)$$

Proof. Since $(\hat{\mathscr{P}}^n, \hat{f}^n)$ is a minimal point of $H_\gamma^n(\delta^n f + \xi^n, \cdot))$ the embedded segmentation $\iota^n(\hat{\mathscr{P}}^n, \hat{f}^n)$ is a minimal point of $\tilde{H}_\gamma^n(f + \iota^n\xi^n, \cdot))$ by Proposition 2 and hence

$$\gamma|\hat{\mathscr{P}}^n| + \|(\iota^n \hat{f}^n - f) - \iota^n\xi^n\|^2 \leq \gamma|\mathscr{Q}| + \|(\iota^n h - f) - \iota^n\xi^n\|^2.$$

Expansion of squares yields that

$$\begin{aligned} & \gamma|\hat{\mathscr{P}}^n| + \|\iota^n \hat{f}^n - f\|^2 + 2\langle\iota^n \hat{f}^n - f, \iota^n\xi^n\rangle + \|\iota^n\xi^n\|^2 \\ \leq \; & \gamma|\mathscr{Q}| + \|\iota^n h - f\|^2 + 2\langle\iota^n h - f, \iota^n\xi^n\rangle + \|\iota^n\xi^n\|^2 \end{aligned}$$

and hence

$$\|\iota^n \hat{f}^n - f\|^2 \leq \gamma(|\mathscr{Q}| - |\hat{\mathscr{P}}^n|) + \|\iota^n h - f\|^2 + 2\langle\iota^n h - \iota^n \hat{f}^n, \iota^n\xi^n\rangle. \quad (12)$$

By definition $h \in \mathscr{F}_{\mathscr{Q}}$ and $\hat{f}^n \in \mathscr{F}_{\hat{\mathscr{P}}^n}$ which implies that $h - \hat{f}^n \in \mathscr{F}' = \operatorname{span}(\hat{\mathscr{P}}^n, \mathscr{F}_{\mathscr{Q}})$ and hence $\pi_{\mathscr{F}'}(\hat{f}^n - h) = \hat{f}^n - h$. We proceed with

$$
\begin{aligned}
&|\langle \iota^n h - \iota^n \hat{f}^n, \iota^n \xi^n \rangle| = |S^n|^{-1} |\langle \pi_{\mathscr{F}'}(\hat{f}^n - h), \xi^n \rangle| = |S^n|^{-1} |\langle h - \hat{f}^n, \pi_{\mathscr{F}'} \xi^n \rangle| \\
\leq\ & \|\iota^n \hat{f}^n - \iota^n h\| \cdot |S^n|^{-1/2} \cdot \|\pi_{\mathscr{F}'} \xi^n\| \\
\leq\ & |S^n|^{-1/2} \|\pi_{\mathscr{F}'} \xi^n\| \cdot \|\iota^n \hat{f}^n - f\| + |S^n|^{-1/2} \|\pi_{\mathscr{F}'} \xi^n\| \cdot \|f - \iota^n h\|.
\end{aligned}
$$

Since $ab \leq a^2 + b^2/4$, we conclude

$$
\begin{aligned}
|\langle \iota^n h - \iota^n \hat{f}^n, \iota^n \xi^n \rangle| &\leq \|\iota^n \hat{f}^n - \iota^n h\|^2/4 + \|f - \iota^n h\|^2/4 + 2\|\pi_{\mathscr{F}'} \xi^n\|^2 / |S^n| \\
&\leq \|\iota^n \hat{f}^n - \iota^n h\|^2/4 + \|f - \iota^n h\|^2/4 + 4 \left(\|\pi_{\hat{\mathscr{P}}^n} \xi^n\|^2 + \|\pi_{\mathscr{Q}} \xi^n\|^2 \right) / |S^n|
\end{aligned}
$$

Putting this into inequality (12) results in

$$
\begin{aligned}
\|\iota^n \hat{f}^n - f\|^2 &\leq \gamma(|\mathscr{Q}| - |\hat{\mathscr{P}}^n|) + \|\iota^n h - f\|^2 + \|\iota^n \hat{f}^n - f\|^2/2 + \|f - \iota^n h\|^2/2 \\
&+ 8 \left(\|\pi_{\hat{\mathscr{P}}^n} \xi^n\|^2 + \|\pi_{\mathscr{Q}} \xi^n\|^2 \right) / |S^n|,
\end{aligned}
$$

which implies the asserted inequality. □

4. Consistency

In this section we complete the abstract considerations and summarize the preliminary work in two theorems on consistency. The first one concerns the desired L^2-convergence of estimates to the ‘truth’, and the second one provides convergence rates.

4.1. L^2-Convergence

We will prove now that the estimates of images converge almost surely to the underlying true signal in $L^2(S^\infty)$ for almost all observations. We adopt the projective setting introduced in Section 3.4. Let us make some agreements in advance.

Hypothesis 1 *Assume that*

(H1.1) there are $\kappa > 0$ and $C > 0$ such that $|\mathscr{R}^n| \geq C \cdot n^\kappa$ eventually,

(H1.2) *the random variables* ξ_s^n *are sub-Gaussian and are such that*

$$\beta = 2 \cdot \sup\{\tau^2(\xi_s^n) : n \in \mathbb{M},\ s \in S^n\} < \infty,$$

(H1.3) *the positive sequence* $(\gamma_n)_{n\in\mathbb{N}}$ *satisfies*

$$\gamma_n \to 0 \text{ and } \gamma_n > C \cdot \frac{\ln|\mathscr{R}^n|}{|S^n|}, \text{ for eventually all } n$$

with $C = \beta D(\kappa+1)/\kappa$, *and* D *is, like in Proposition 1, an upper bound for the dimension of the linear spaces* $\mathscr{F}_P$.

Remark. Note that the condition $\gamma_n \cdot |S^n|/\ln n \to \infty$ implies the second part of (H1.3) by (H1.1). It was used for example in F. FRIEDRICH [20] or L. BOYSEN et al. [34].

Given a signal $f \in L^2(S^\infty)$ we must assure that our setting actually allows for good approximations of f at all. If so, least squares estimates are consistent.

Theorem 4 *Assume that Hypothesis 1 holds. Let* $f \in L^2(S^\infty)$ *and suppose*

$$\lim_{k\to\infty} \limsup_{n\to\infty} \inf_{(\mathscr{Q},h)\in\mathfrak{S}^n, |\mathscr{Q}|\le k} \|\iota^n h - f\|^2 = 0. \tag{13}$$

Then

$$\|\iota^n \hat{f}^n(\omega) - f\|^2 \longrightarrow 0 \quad \text{as } n \to \infty \text{ for almost all } \omega \in \Omega.$$

We formulate part of the proof separately, since it will be needed later once more.

Lemma 2 *We maintain the assumptions of Theorem 4. Then, given* $k > 0$,

$$\|\iota^n \hat{f}^n(\omega) - f\|^2 \le 3\gamma_n \cdot k + 3\|\iota^n h - f\|^2 \text{for all } (\mathcal{Q},h) \in \mathfrak{S}^n \text{ such that } |\mathcal{Q}| \le k \tag{14}$$

eventually for all $n \in \mathbb{N}$ *and for almost all* $\omega \in \Omega$.

Proof. Lemma 1 yields

$$\|\iota^n \hat{f}^n(\omega) - f\|^2 \le 2\gamma_n \left(|\mathscr{Q}| - |\mathscr{P}^n|\right) + 3\|\iota^n h - f\|^2 + \frac{16}{n^d}\left(\|\pi_{\hat{\mathscr{P}}^n}\xi\|^2 + \|\pi_{\mathscr{Q}}\xi\|^2\right)$$

and application of Proposition 1 implies that for any real number $C' > \frac{\kappa+1}{\kappa}\beta D$, the following inequality holds for almost all $\omega \in \Omega$

$$\begin{aligned}\|\iota^n \hat{f}^n(\omega) - f\|^2 &\leq 2\gamma_n k + 3\|\iota^n h - f\|^2 + 16C' \left(\frac{\ln(|\mathscr{R}^n|)}{n^d}\right) \cdot \left(|\mathscr{Q}| + |\hat{\mathscr{P}}^n|\right) - 2\gamma_n \cdot |\hat{\mathscr{P}}^n| \\ &\leq 2\gamma_n k + 3\|\iota^n h - f\|^2 + 16C' \frac{\ln|\mathscr{R}^n|}{n^d} k + |\mathscr{P}^n| \left(8C' \frac{\ln|\mathscr{R}^n|}{n^d} - 2\gamma_n\right)\end{aligned}$$

For γ_n satisfying Hypothesis (H1.3), the term in parenthesis is negative. Therefore (14) holds and the assertion is proved. □

Theorem 4 follows now easily.

Proof of Theorem 4. The following formulae hold almost surely. Lemma 2 implies that, for

$$\|\iota^n \hat{f}^n - f\|^2 \leq 3\gamma_n \cdot k + 3 \cdot \inf_{(\mathscr{Q},h)\in\mathfrak{S}^n, |\mathscr{Q}|\leq k} \left(\|\iota^n h - f\|^2\right) \text{ eventually}$$

Therefore

$$\begin{aligned}\limsup_{n\to\infty} \|\iota^n \hat{f}^n - f\|^2 &\leq \limsup_{n\to\infty} \left(3\gamma_n \cdot k + 3 \cdot \inf_{(\mathscr{Q},h)\in\mathfrak{S}^n, |\mathscr{Q}|\leq k} \left(\|\iota^n h - f\|^2\right)\right) \\ &= 0 + 3 \cdot \limsup_{n\to\infty} \inf_{(\mathscr{Q},h)\in\mathfrak{S}^n, |\mathscr{Q}|\leq k} \left(\|\iota^n h - f\|^2\right)\end{aligned}$$

By assumption (13), the right hand side converges to 0 as k tends to ∞. Hence

$$\limsup_{n\to\infty} \|\iota^n \hat{f}^n - f\|^2 = 0,$$

which completes the proof. □

4.2. Convergence Rates The final abstract result provides almost sure convergence rates in the general setting.

Theorem 5 *Suppose that Hypothesis 1 holds and assume further that there are real numbers $\alpha, C > 0, \varrho \geq 0$, and a sequence $(F_n)_{n\in\mathbb{N}}$ with $\lim_{n\to\infty} F_n = \infty$ such that*

$$\|\iota^n h - f\| \leq C \cdot \left(\frac{k^\varrho}{F_n} + \frac{1}{k^\alpha}\right) \tag{15}$$

for all $n \in \mathbb{M}$ and k, and some $(\mathscr{Q}, h) \in \mathfrak{S}^n$ with $|\mathscr{Q}| \leq k$.

Then

$$\|\iota^n \hat{f}^n(\omega) - f\|^2 = O\left(\gamma_n^{\frac{2\alpha}{2\alpha+1}}\right) + O\left(F_n^{-\frac{2\alpha}{\alpha+\varrho}}\right) \text{ for almost all } \omega \in \Omega. \tag{16}$$

Proof. Let $(k_n)_{n\in\mathbb{M}}$ be a sequence in $\mathbb{R}_+$. Recall from Lemma 2 that

$$\|\iota^n \hat{f}^n - f\|^2 \leq 2\gamma_n \cdot k_n + 3 \cdot \|\iota^n h - f\|_2^2$$

for sufficiently large $n \in \mathbb{M}$ and any $(\mathscr{Q}, h) \in \mathfrak{S}^n$ with $|\mathscr{Q}| \leq k_n$ on a set of ω of full measure. The following arguments hold for all such ω. We will write C for constants; hence the C below may differ.

Since $(a+b)^2 \leq 2(a^2+b^2)$, assumption (15) implies that

$$\|\iota^n \hat{f}^n - f\|^2 \leq C\left(\gamma_n \cdot k_n + \frac{k_n^{2\varrho}}{F_n^2} + \frac{1}{k_n^{2\alpha}}\right). \tag{17}$$

This decomposition of the error can be interpreted as follows: the first term corresponds to an estimate of the error due to the noise, the second term corresponds to the discretization while the third term can be directly related to the approximation error of the underlying scheme, in the continuous domain.

One has free choice of the parameters k_n. We enforce the same decay rate for the first and third term setting $\gamma_n k_n = k_n^{-2\alpha}$ Then, in view of (17),

$$\|\iota^n \hat{f}^n - f\|^2 \leq C\left(\gamma_n^{\frac{2\alpha}{2\alpha+1}} + \frac{\gamma_n^{-\frac{2\varrho}{2\alpha+1}}}{F_n^2}\right). \tag{18}$$

To get the same rate for the discretisation and the approximation error set

$$\frac{k_n^{2\varrho}}{F_n^2} = \frac{1}{k_n^{2\alpha}} \text{ or equivalently } k_n = F_n^{\frac{1}{\varrho+\alpha}},$$

which, together with estimate (17), yields

$$\|\iota^n \hat{f}^n - f\|^2 \leq C\left(\gamma_n F_n^{\frac{1}{\varrho+\alpha}} + F_n^{-\frac{2\alpha}{\alpha+\varrho}}\right). \tag{19}$$

Straightforward calculation gives

$$\gamma_n^{\frac{2\alpha}{2\alpha+1}} \geq \frac{\gamma_n^{-\frac{2\varrho}{2\alpha+1}}}{F_n^2} \text{ if and only if } \gamma_n F_n^{\frac{1}{\alpha+\varrho}} \geq \frac{1}{F_n^{\frac{2\alpha}{\alpha+\varrho}}}$$

Hence, the first term on the right hand side of inequality (18) dominates the second one if and only this holds in inequality (19). We discriminate between the two cases $\geq$ and $<$. The first one is

$$\gamma_n^{\frac{2\alpha}{2\alpha+1}} \geq \frac{\gamma_n^{-\frac{2\varrho}{2\alpha+1}}}{F_n^2}. \tag{20}$$

Combination with (18) results in

$$\|\iota^n \hat{f}^n - f\|_2^2 \leq C \cdot \gamma_n^{\frac{2\alpha}{2\alpha+1}} \tag{21}$$

for some $C > 0$. In view of the equivalence, replacement of $\geq$ by $<$ in (20), results in

$$\gamma_n F_n^{\frac{1}{\alpha+\varrho}} < F_n^{-\frac{2\alpha}{\alpha+\varrho}}.$$

which, together with estimate (19), gives for some $C > 0$ that

$$\|\iota^n \hat{f}^n - f\|^2 \leq C \cdot F_n^{-\frac{2\alpha}{\alpha+\varrho}}. \tag{22}$$

Combination of (22) and (21) completes the proof of (16). □

Remark 4 Let us continue from Remark 3. If $|\mathscr{R}^n| \sim n^\kappa$ and noise is white Gaussian with $\beta = 2\sigma^2$ then Hypothesis (H1.3) boils down to

$$\gamma_n \longrightarrow 0 \text{ and } \gamma_n > 2(\kappa+1)\sigma^2 D \cdot \frac{\ln n}{n^d}.$$

Setting $\varepsilon_n = \sigma/n^{d/2}$, the estimate (16) then reads

$$\|\iota^n \hat{f}^n(\omega) - f\|^2 = O\left(\left(\varepsilon_n^2 \,|\ln \varepsilon_n|\right)^{\frac{2\alpha}{2\alpha+1}}\right),$$

as long as the growth of F_n is sufficient. This is strongly connected with the optimal minimax rates from model selection, which bound the expectations of the left hand side, see for instance L. BIRGÉ and P. MASSART [1].

5. Special Segmentations

We are going now to exemplify the abstract Theorem 5 by way of typical partitions and spaces of functions. On the one hand, this extends a couple of already existing results and, on the other hand, it illustrates the wide range of possible applications.

5.1. One Dimensional Signals - Interval Partitions

Albeit focus of this paper is on two or more dimensions, we start with one dimension. There are at least two reasons for that: illustration of the abstract results by choices of the (seemingly) most elementary example, and to generalize results like some of those in L. BOYSEN et al. [34] to classes of piecewise Sobolev functions.

To be definite, let $S^n = \{1, \ldots, n\}$ and let $\mathscr{R}^n = \{[i, j] : 1 \leq i \leq j \leq n\}$ be the discrete intervals of admissible fragments. Then $\mathfrak{P}^n$ is the collection of partitions of S^n into intervals. Plainly, $|\mathscr{R}^n| = (n+1)n/2$ and $|\mathfrak{P}^n| = 2^{n-1}$. We deal with approximation by local polynomials. To this end and in accordance with Section 3.4, we choose the finite dimensional linear subspace $\mathscr{F}_p \subset L^2([0, 1))$ of polynomials of maximal degree p. The induced segmentation classes $\mathfrak{S}^n(\mathfrak{P}^n, \mathfrak{F}^n)$ consist of piecewise polynomial functions relative to partitions in $\mathfrak{P}^n$.

The signals to be estimated will be members of the fractional Sobolev space $W^{\alpha,2}((0, 1))$ of order $\alpha > 0$. The main task is to verify Condition (15). Note that this class of functions is slightly larger than the classical Hölder spaces of order α usually treated. For results in the case of equidistant partitioning, we refer, for instance, to L. GYÖRFI et al. [24] Section 11.2.

For the following lemma, we adopt classical arguments from approximation theory.

Lemma 3 *For any $f \in W^{\alpha,2}((0, 1))$, with $p < \alpha < p + 1$, there is $C > 0$ such that for all $k \leq n \in \mathbb{N}$, there is $(\mathscr{P}^n_k, h^n_k,) \in \mathfrak{S}^n$, such that $|\mathscr{P}^n_k| \leq k$ and which satisfies*

$$\|f - \iota^n h^n_k\| \leq C \cdot \left(\frac{1}{k^\alpha} + \frac{k}{n}\right) \tag{23}$$

For the proof, let us introduce partitions $\mathscr{I}_k = \{[(i-1)/k, i/k) : i = 1, \cdots, k\}$ of $[0, 1)$ into k intervals, each of length $1/k$.

Proof. Let $f \in W^{\alpha,2}((0, 1))$. From classical approximation theory (see e.g. [15], Chapter 12, Thm. 2.4), we learn that there is $C > 0$ such that there is a piecewise polynomial function h_k of degree at most p such that

$$\|f - h_k\| \leq \frac{C}{k^\alpha}.$$

For each $i = 1, \dots, k$, let $h_{k,i}$ denote the restriction of h_k to $I_i = ((i-1)/k, i/k)$. We consult the Bramble-Hilbert lemma (for a version corresponding to our needs, we refer to Thm. 6.1 in [18]) and find $C > 0$, such that

$$|f - h_{k,i}|_{W^{1,2}(I_i)} \leq C \cdot |f|_{W^{1,2}(I_i)} \text{ for each } i = 1, \dots, k.$$

This yields for some $C > 0$, independent of k and n, that

$$|h_{k,i}|_{W^{1,2}(I_i)} \leq |f - h_{k,i}|_{W^{1,2}(I_i)} + |f|_{W^{1,2}(I_i)} \leq C \cdot |f|_{W^{1,2}(I_i)} \text{ for all } i = 1, \cdots, k.$$

We turn now to the piecewise constant approximation on the partition $\mathscr{I}_n$. We split $[0,1)$ into the union J_k^n of those intervals in $\mathscr{I}_n$ which do not contain knots i/k and the union K_k^n of those intervals in $\mathscr{I}_n$ which do contain knots i/k. For $I \in \mathscr{I}_k$ and $I \subset J_k^n$, we have

$$|h_{k,i}|_{W^{1,2}(I)} \leq C|f|_{W^{1,2}(I)}| \quad \text{if and only if} \quad |h'_{k,i}|^2_{L^2(I)} \leq C^2 \cdot |f'|^2_{L^2(I)}.$$

This implies

$$\sum_{I \subset J_n^k} |h'_{k,i}|^2_{L^2(I)} \leq C^2 \sum_{I \subset J_n^k} |f'|^2_{L^2(I)} \leq C^2 |f'|_{L^2([0,1])},$$

which in turn leads to

$$|h_k|_{W^{1,2}(J_n^k)} \leq C^2 |f|_{W^{1,2}((0,1))}.$$

Hence we are ready to conclude that for some constant $C > 0$,

$$\|h_k - \iota^n \delta^n h_k\|_{L^2(J_k^n)} \leq C/n. \tag{24}$$

For $I \in \mathscr{I}_k$ and $I \subset K_k^n$, we use the fact that $h_k^n \leq 2C \cdot \|f\|_{L^\infty}([0,1])$ and deduce

$$\|h_k - \iota^n \delta^n h_k\|_{L^2(I)} \leq 2C \|f\|_{L^\infty(I)}/n.$$

Summation over all intervals included in K_k^n results in

$$\|h_k - \iota^n \delta^n h_k\|_{L^2(K_k^n)} \leq C \cdot k/n.$$

This yields for the entire interval $[0,1)$ that

$$\|f - \iota^n \delta^n h_k\| \leq \|f - h_k\| + \|h_k - \iota^n \delta^n h_k\| \leq C \left(\frac{k}{n} + \frac{1}{k^\alpha} \right).$$

With $h_k^n = \delta^n h_k$, this completes the proof. □

Piecewise smooth functions have only a very low Sobolev regularity. Indeed, recall that piecewise smooth functions belong to $W^{\alpha,2}((0,1))$ only for $\alpha > 1/2$. In order to overcome this limitation, we consider a larger class of functions, the class of piecewise Sobolev functions.

Definition 1 *Let $\alpha > 1/2$ be a real number, $J \in \mathbb{N}$, and $x_0 = 0 < x_1 < \cdots < x_{J+1} = 1$. A function f is said to be* piecewise $W^{\alpha,2}([0,1])$ with J jumps, *relative to the partition $\{[x_i, x_{i+1}) : i = 1, \cdots, J\}$ if*

$$f|_{(x_i,x_{i+1})} \in W^{\alpha,2}\left((x_i, x_{i+1})\right)$$

Remark 5 *Definition 1 is consistent, due to the Sobolev embedding theorem. For an open interval I of $\mathbb{R}$, $W^{\alpha,2}(I)$ is continuously embedded into $\mathscr{C}(I^a)$, the space of uniformly continuous functions on the closure I^a of I.*

We conclude from Lemma 3:

Lemma 4 *Let f be piecewise-$W^{\alpha,2}([0,1))$ with J jumps and with $p < \alpha < p+1$. Then there are $C > 0$ and $(\mathscr{P}_k^n, h_k^n) \in \mathfrak{S}^n$, such that $|\mathscr{P}^n| \le k$ and*

$$\|f - h_k^n\| \le C \cdot \left(\frac{1}{k^\alpha} + \frac{k}{n} + \frac{J}{n}\right). \tag{25}$$

Proof. With the same arguments as in the proof of Lemma (3) we just have to incorporate the error made at each jump of the original piecewise regular function. More precisely, we use a similar splitting into J_k^n and K_k^n where K_k^n also contains the intervals containing x_i for $i = 1, \cdots, J$. Since there are at most $k + J$ intervals in K_k^n, this gives estimate (25). □

By Lemma 4, a piecewise Sobolev function satisfies Condition (15) with $\rho = 1$ and $F_n = n$ and therefore Theorem 5 applies. In summary

Theorem 6 *Let $\alpha \in (0, p+1)$ where p is the maximal degree of the approximating polynomials and let f be piecewise $W^{\alpha,2}([0,1])$. We assume further that (H1.3) holds and that the noise variables ξ_s^n from Section 2.1 satisfy (8). Then*

$$\|\iota^n \hat{f}^n(\omega) - f\|^2 = O\left(\gamma_n^{\frac{2\alpha}{2\alpha+1}}\right), \text{ for almost all } \omega \in \Omega. \tag{26}$$

Proof. Let us check the assumption in Theorem 5. Since $|\mathscr{R}| = (n-1)n/2$, Hypothesis *(H1.1)* holds with $\kappa = 2$. Hypothesis *(H1.2)* and *(H1.3)* were required separately. Finally, Condition (15) holds with $\varrho = 1$ and $F_n = n$ by Lemma 4. Finally, Hypothesis *(H1.3)* completes the proof. □

Let $\mathscr{C}^1([0,1])$ denote the set of continuously differentiable functions. For $p \in \mathbb{N}$, $\alpha \in (p, p+1]$, a function $f \in \mathscr{C}^p([0,1])$ is said to be α-*Hölder* if there is $C > 0$ such that

$$|f^{(p)}(x) - f^{(p)}(y)| \leq C|x-y|^{\alpha - p} \text{ for any } x, y \in [0,1], x \neq y.$$

The linear space of α-Hölder functions will be denoted by $\mathscr{C}^\alpha([0,1])$ if $\alpha \in \mathbb{N}$ and $\mathscr{C}^{\alpha-1,1}([0,1])$ if $\alpha \in \mathbb{N}$.

Remark. Choose $\gamma_n = C \ln n/n$ with large enough C, independently of f. Then the almost sure estimates (26) of the estimation error simplifies to

$$\|\iota^n \hat{f}^n(\omega) - f\|^2 = O\left(\frac{\ln n}{n}\right)^{\frac{\alpha}{2\alpha+1}} \text{ for almost all } \omega \in \Omega. \tag{27}$$

These convergence rates are, up to the logarithmic factor, the optimal rates for mean square error in the Hölder classes $\mathscr{C}^\alpha([0,1])$. Thus, our estimate adapts automatically to the smoothness of the signal.

5.2. Wedgelet Partitions

Wedgelet decompositions are content-adapted partitioning methods based on elementary geometric atoms, called *wedgelets*. A wedge results from the splitting of a square into two pieces by a straight line and in our setting a wedgelet will be a piecewise polynomial function over a wedge partition. The discrete setting requires a careful treatment. We adopt the discretization scheme from F. FRIEDRICH et al. [21], which relies on the digitalization of lines from J. BRESENHAM [5]. This discretization differs from that in D. DONOHO [16], where all pairs of pixels on the boundary of a discrete square are used as endpoints of line segments. One of the main reasons for our special choice is an efficient algorithm which returns exact solutions of the functional (6). It relies on rapid moment computation, based on lookup tables, cf. F. FRIEDRICH et al. [21].

5.2.1. Wedgelet partitions

Let us first recall the relevant concepts and definitions. Only the case of dyadic wedgelet partitions will be discussed. Generalizations are straightforward but technical.

We start from discrete dyadic squares $S^m = \{1, \dots, m\}^2$ with $m \in \mathbb{M} = \{2^p : p \in \mathbb{N}_0\}$. *Admissible fragments* are dyadic squares of the form

$$[(i-1)\cdot 2^q, i\cdot 2^q) \times [(j-1)\cdot 2^q, j\cdot 2^q), \quad 1 \le i, j \le 2^{p-q},\ 0 \le q \le p.$$

The collection of dyadic squares can be interpreted as the set of leaves of a quadtree where each internal node has exactly four children obtained by subdividing one square into four.

Digital lines in $\mathbb{Z}^2$ are defined for angles $\vartheta \in (-\pi/4, 3\pi/4]$. Let

$$d(\vartheta) = \max\{|\cos\vartheta|, |\sin\vartheta|\}, \quad v(\vartheta) = \begin{cases} (-\sin\vartheta, \cos\vartheta) & \text{if } |\cos\vartheta| \ge |\sin\vartheta| \\ (\sin\vartheta, -\cos\vartheta) & \text{otherwise} \end{cases}.$$

The *digital line through the origin in direction* ϑ is defined as

$$L^0_\vartheta = \{s \in \mathbb{Z}^2 : -d(\vartheta)/2 < \langle s, v(\vartheta)\rangle \le d(\vartheta)/2\}.$$

Lines parallel to L^0_ϑ are shifted versions

$$L^r_\vartheta = \{s \in \mathbb{Z}^2 : (r-1/2)d(\vartheta) < \langle s, v(\vartheta)\rangle \le (r+1/2)d(\vartheta)\}$$

with the *line numbers* $r \in \mathbb{Z}$. One distinguishes between *flat* lines where $\cos\vartheta \ge \sin\vartheta$ and *steep* lines where $\cos\vartheta < \sin\vartheta$. For $x \in \mathbb{R}$, set $\mathtt{round}(x) = \max\{i \in \mathbb{Z} : i \le x + 1/2\}$, let $y_\vartheta(x) = \mathtt{round}(x \cdot \tan\vartheta)$ and $x_\vartheta(x) = \mathtt{round}(y \cdot \cot\vartheta)$. According to Lemma 2.7 in F. FRIEDRICH et al. [21],

$$\begin{aligned} L^r_\vartheta &= (0, r) + \{(x, y_\vartheta(x) : x \in \mathbb{Z})\} \text{ for flat lines,} \\ L^r_\vartheta &= (r, 0) + \{(x_\vartheta(y), y : y \in \mathbb{Z})\} \text{ for steep lines.} \end{aligned}$$

By Lemma 2.8 in the same reference, all parallel lines partition $\mathbb{Z}^2$. We are now ready to define wedgelets. Let Q be a square in $\mathbb{Z}^2$ and L^r_ϑ a line with $L^r_\vartheta \cap Q \neq \emptyset$ and $L^{r+1}_\vartheta \cap Q \neq \emptyset$. A *wedge split* is a partition of Q into the *lower* and *upper wedge*, respectively, given by

$$W^{r,l}_\vartheta = \bigcup_{k \le r} L^k_\vartheta \cap Q, \quad W^{r,u}_\vartheta = \bigcup_{k > r} L^k_\vartheta \cap Q. \tag{28}$$

Let $\mathscr{Q}$ be a partition of some domain S^m into squares. Then a *wedge partition* of S^m is obtained replacing some of these squares by the two wedges of a wedge split. It is called *dyadic* if $m \in \mathbb{M}$, and the squares $Q \in \mathscr{Q}$ are dyadic.

We assume that a finite set Θ of angles is given. The set $\mathscr{R}^m$ of admissible segments consists of wedges obtained by wedge splits of dyadic squares, given by (28) and for $\theta \in \Theta$, or by dyadic squares.

Focus is on piecewise polynomial approximation of low order. The induced segmentation classes $\mathfrak{S}^m$ consist of piecewise polynomial functions relative to a wedgelet partition. The cases of piecewise constant (original wedgelets) and piecewise linear polynomials (platelets) will be treated explicitly.

5.2.2. Wedgelets and approximations

We first recall some approximation results for wedgelets. They stem from D. DONOHO [16] and R. WILLETT and R. NOWAK [35]. Since we are not working with the same discretization we rewrite them for the continuous setting and provide elementary self-contained proofs. The discussion of the discretization is postponed to Section 5.2.3. . We start with the definition of horizon functions, like in D. DONOHO [16].

Definition 2 (Horizon functions) *Let $\alpha \in (1,2]$ and $h \in \mathscr{C}^\alpha([0,1])$ if $\alpha < 2$ or $\mathscr{C}^{1,1}([0,1])$ if $\alpha = 2$. Let further f be a bivariate function which is piecewise constant relative to the partition of $[0,1]^2$ in an upper and a lower part induced by h:*

$$f(x,y) = \begin{cases} c_1 \text{ if } y \le h(x), \\ c_2 \text{ if } y > h(x), \end{cases}$$

*with real numbers c_1 and c_2. Such a function is called an α-*horizon function*; the set of such functions will be denoted by $Hor^\alpha([0,1]^2)$. h is called the* horizon boundary *of f.*

Discretization at various levels of a typical horizon function is plotted in Fig. 2, left column. In the right column respective noisy versions are shown.

Lemma 5 *Let $\alpha \in [1,2]$ and $f \in Hor^{\alpha}([0,1]^2)$ with boundary function h. Then there are $C, C' > 0$ - independent of k - and for each k a continuous wedge partition $\mathscr{W}_k$ of the unit square $[0,1]^2$, such that $|\mathscr{W}_k| \leq C'k$ and*

$$\|f - f_k\|_{L^2([0,1]^2)} \leq \frac{C}{k^{\alpha/2}},$$

where f_k is the L^2-projection of f on the space of piecewise constant functions relative to the wedge partition $\mathscr{W}_k$.

Proof. Let us first approximate the graph of h by linear pieces. We consider the uniform partition induced by $x_i = i/k$. We denote by $S_k(h)$ the continuous linear spline interpolating h relatively to the uniform subdivision:

$$S_k(h)(x) = h(x_i) + (x - x_i)\left(\frac{h(x_{i+1}) - h(x_i)}{x_{i+1} - x_i}\right) \text{ for } i = 0, \ldots, k-1 \text{ and } x \in I_i$$

where $I_i = [x_i, x_{i+1}]$. Therefore, we have

$$|h(x) - S_k(h)(x)| = \left|h(x) - h(x_i) - \frac{h(x_{i+1}) - h(x_i)}{x_{i+1} - x_i}(x - x_i)\right| \text{ for each } x \in I_i. \tag{29}$$

Since $h' \in \mathscr{C}^{0,\alpha-1}([0,1])$, there exists $C > 0$ such that

$$\left|\frac{h(x_{i+1}) - h(x_i)}{x_{i+1} - x_i} - h'(x_i)\right| \leq C|x_{i+1} - x_i|^{\alpha-1} = \frac{C}{k^{\alpha-1}}.$$

This implies that

$$|h(x) - S_k(h)(x)| = \left|h(x) - h(x_i) - \left(h'(x_i) + O\left(\frac{1}{k^{\alpha-1}}\right)\right)(x - x_i)\right| \text{ for } x \in I_i.$$

On the other hand,

$$h(x) = h(x_i) + h'(x_i)(x - x_i) + O(|x - x_i|^{\alpha}).$$

Hence, Equation (29) can be rewritten as

$$|h(x) - S_k(h)(x)| = O(|x - x_i|^{\alpha}) + O\left(\frac{1}{k^{\alpha}}\right)$$

and there is a constant $C > 0$ (independent of k) such that

$$\|h - S_k(h)\|_{L^{\infty}([0,1])} \leq \frac{C}{k^{\alpha}}.$$

Now we will use this estimate to derive error bounds for the optimal wedge representation. As a piecewise approximation of f we propose

$$f_k(x,y) = \begin{cases} c_1 \text{ if } y < S_k(h)(x); \\ c_2 \text{ if } y > S_k(h)(x). \end{cases}$$

We bound the error by the area between the horizon h and its piecewise affine reconstruction:

$$\begin{aligned} \|f - f_k\|_{L^2([0,1]^2)} &\leq |c_1 - c_2| \left(\int_0^1 |h(x) - S_k(h)(x)| \, dx \right)^{1/2} \\ &\leq |c_1 - c_2| \left(\|h - S_k(h)\|_{L^\infty([0,1])} \right)^{1/2} \leq \frac{C}{k^{\alpha/2}}. \end{aligned}$$

It remains to bound the size of the minimal continuous wedgelet partition $\mathscr{W}_k$, such that $f_k \in \mathscr{F}_{\mathscr{W}_k}$. A proof is given in Lemma 4.3 in D. Donoho [16]; it uses $h \in \mathscr{C}^1([0,1])$. □

Remark. For an arbitrary horizon function, the approximation rates obtained by non-linear wavelet approximation (with sufficiently smooth wavelets) can not be better than

$$\|f - f_k\|_{L^2([0,1]^2)} = O\left(\frac{1}{k^{1/2}}\right),$$

where f_k is the non-linear k-term wavelet approximation of f. This means that for such a function the asymptotical behaviour in terms of approximation rates is strictly better for wedgelet decompositions than for wavelet decompositions. For a discussion on this topic, see Section 1.3 in E. Candès and D. Donoho [8].

Piecewise constant wedgelet representations are limited by the degree 0 of the regression polynomials on each wedge. This is reflected by the choice of the horizon functions which are not only piecewise smooth but even piecewise constant. A similar phenomenon arises also in the case of approximation by Haar wavelets.

R. Willett and R. Nowak [35] extended the regression model to piecewise linear functions on each leaf of the wedgelet partition and called the according representations *platelets*. This allows for an improved approximation rate for larger classes of piecewise smooth functions.

Let h be a function in $\mathscr{C}([0,1])$. We define the two subdomains S^+ and S^-, respectively, as the hypograph and the epigraph of h restricted to $(0,1)^2$. In other words:

$$S^+ = \left\{(x,y) \in (0,1)^2 \mid y > h(x)\right\}, \ S^- = \left\{(x,y) \in (0,1)^2 \mid y < h(x)\right\}. \quad (30)$$

Let us introduce the following generalised class of horizon functions:

$$Hor_1^\alpha([0,1]^2) := \{f : [0,1]^2 \to \mathbb{R} |\ f|_{S^+} \text{ and } f|_{S^-} \in \mathscr{C}^\alpha(S^\pm), h \in \mathscr{C}^\alpha([0,1])\}. \quad (31)$$

The following result from R. WILLETT and R. NOWAK [35] gives approximation rates by platelet approximations for Hor^α.

Proposition 3 *Let $f \in Hor_1^\alpha([0,1])$ for $1 < \alpha \leq 2$. Then the k-term platelet approximation error h_k satisfies*

$$\|f - h_k\|_{L^2([0,1]^2)} = O\left(\frac{1}{k^{\alpha/2}}\right). \quad (32)$$

Proof. A sketch of the proof is given by the following two steps: (1) the boundary between the two areas is approximated uniformly like in D. DONOHO [16]; (2) in the rest of the areas we use also uniform approximation with dyadic cubes, together with the corresponding Hölder bounds. The partition generated consists of squares of sidelength at least $O(1/k^{1/2})$. There are at most $O(k)$ such areas. □

5.2.3. Wedgelets and consistency

Now we apply the continuous approximation results to the consistency problem of the wedgelet estimator based on the above discretization. Note that, due to our specific discretization, the arguments below differ from those in D. DONOHO [16].

Two ingredients are needed: pass over to a suitable discretisation and bound the number of generated discrete wedgelet partitions polynomially in n, in order to apply the general consistency results. Let us first state a discrete approximation lemma:

Lemma 6 *Let f be an α horizon function in Hor_1^α with $1 < \alpha < 2$. There is $C > 0$ such that for all $k \le n \in \mathbb{N}$, there is $(\mathscr{P}_k^n, h_k^n,) \in \mathfrak{S}^n$, such that $|\mathscr{P}_k^n| \le k$ and which satisfies*

$$\|f - \iota^n h_k^n\| \le C \cdot \left(\frac{1}{k^{\alpha/2}} + \frac{k^{1/2}}{n^{1/2}} \right). \tag{33}$$

Proof. The triangular inequality yields the following decomposition of the error

$$\|f - \iota^n \delta^n h_k\| \le \|f - h_k\| + \|h_k - \iota^n \delta_n h_k\|.$$

The first term may be approximated by (32), whereas the second term corresponds to the discretisation. Let us estimate the error induced by discretisation.

One just has to split $[0,1)^2$ into J_n^k, the union of those squares in $\mathscr{Q}_n$ which do not intersect the approximating wedge lines and K_n^k the union of such squares meeting the approximating wedge lines. We obtain the following estimates:

$$\|h_k - \iota^n \delta^n h_k\|^2_{L^2(Q)} \le \frac{C}{n^2} \text{ for any } Q \in K_n^k, \text{ and for some constant } C > 0.$$

Since there are at most $C'kn$ such squares, for some constant C' not depending on k and n, this implies that

$$\|h_k - \iota^n \delta^n h_k\|^2_{L^2(K_n^k)} \le \frac{Ckn}{n^2} = \frac{C}{n} \text{ and } \|h_k - \iota^n \delta^n h_k\|^2_{L^2(J_k^n)} \le \frac{Ck}{n},$$

where $C > 0$ is a constant. Taking $h_k^n = \delta^n h_k$ completes the proof. □

Finally, the following lemma provides an estimate of the number of fragments in $\mathscr{R}^n$.

Lemma 7 *There is a constant $C > 0$ such that for all $n \in \mathbb{M}$ the number $|\mathscr{R}^n|$ of fragments used to form the wedgelet partitions is bounded as follows:*

$$|\mathscr{R}^n| \le Cn^4.$$

Proof. In a dyadic square of size j, there are at most j^4 possible digital lines. For dyadic $n \in \mathbb{M}$ one can write $n = 2^J$ and therefore we have

$$|\mathscr{R}^n| \le \sum_{i=0}^{J} 2^{2(J-i)} \cdot 2^{2\cdot 2i} = n^2 \sum_{i=0}^{J} 2^{2i} = n^2 \cdot \frac{2^{2J+2} - 1}{2^2 - 1} \le C \cdot n^4 \text{ for some constant } C > 0.$$

This completes the proof. $\square$

Note that the discretization of the continuous approximation h_k leads to a wedgelet partition composed of fragments in $\mathscr{R}^n$. Therefore, combination of the Lemmata 7 and 6 yields:

Theorem 7 *Let $\alpha \in (1, 2)$ and let f be an α horizon function in $Hor_1^\alpha([0, 1]^2)$. Assume further that the noise is such that (H1.2) holds and suppose that the parameters γ_n satisfy (H1.3) with $\kappa = 4$. Then*

$$\|\hat{f}^n_{\gamma_n} - f\|^2 = O\left(\gamma_n^{\frac{\alpha}{\alpha+1}}\right) + O\left(n^{-\frac{\alpha}{\alpha+1}}\right), \text{ for almost all } \omega \in \Omega, \tag{34}$$

where $\hat{f}^n_{\gamma_n}$ is the wedgelet-platelet estimator.

Remark 6 *Choosing γ_n of the order $\ln n/n^2$, estimate (34) reads*

$$\|\hat{f}^n_{\gamma_n} - f\|^2 = O\left(\frac{(\ln n)^{\frac{2\alpha}{\alpha+1}}}{n^{\frac{2\alpha}{\alpha+1}}}\right) + O\left(\frac{1}{n^{\frac{\alpha}{\alpha+1}}}\right) \text{ for almost all } \omega \in \Omega. \tag{35}$$

Whereas the first term on the right-hand size consists of the best compromise between approximation and noise removal, the second term on the right-hand size corresponds to the discretization error. Note that, in contrast to the $1D$-case the discretization error asymptotically dominates the first term. This is related to the piecewise constant nature of the discretization. In concrete applications, this may severly limit the actual quality of the estimation. Neglecting this discretization problem, the decay rates given by (35) are the usual optimal rates for the function class under consideration.

On the left column of Fig. 3, wedgelet estimators for a typical noisy horizon function are shown.

5.3. Triangulations

Adaptive triangulations have been used since the emergence of early finite element methods to approximate solutions of elliptic differential equations. They have been also used in the context of image approximation; we refer to L. DEMARET and A. ISKE [12] for an account on recent triangulation methods applied to image approximation. The idea to use discrete triangulations leading to partitions based on a polynomially growing number of triangles has been proposed in E. CANDÈS [7] in the context of piecewise constant functions over triangulations. In the present example, we deal with a different approximation scheme, where the triangulations are Delaunay triangulations and were the approximating functions are continuous linear splines. One key ingredient is the use of recent approximation results, L. DEMARET and A. ISKE [13], that show the asymptotical optimality of approximations based on Delaunay triangulations having at most n vertices. Due to this specific approximation context, a key feature for the proof of the consistency is a suitable discretization scheme, which still preserves the approximation property.

5.3.1. Continuous and discrete triangulations

Let us start with some definitions. We begin with triangulations in the continuous settings:

Definition 3 *A* conforming triangulation $\mathcal{T}$ *of the domain* $[0,1]^2$ *is a finite set* $\{T\}_{T\in\mathcal{T}}$ *of closed triangles* $T \subset [0,1]^2$ *satisfying the following conditions.*

(i) The union of the triangles in $\mathcal{T}$ *covers the domain* $[0,1]^2$*;*

(ii) for each pair $T, T' \in \mathcal{T}$ *of distinct triangles, the intersection of their interior is empty;*

(iii) any pair of two distinct triangles in $\mathcal{T}$ *intersects at most in one common vertex or along one common edge.*

We denote the set of (conforming) triangulations by $\mathscr{T}([0,1]^2)$*. We will use the term* triangulations *for conforming triangulations.*

Accordingly we define the following discrete sets, relatively to partitions $\mathscr{Q}_k = \{[(i-1)/k, i/k) \times [(j-1)/k, j/k) : i,j = 1,\cdots,k\}$ of $[0,1)^2$ into k squares each of side length $1/k$.

For $a, b \in [0,1]^2$ we denote by $[a,b]$ the line segment with endpoints a and b.

Definition 4 *For a triangle* $T \subset [0,1]^2$*, with vertices* a, b *and* c*, we define the following discrete sets:*

(i) for each $p \in \{a,b,c\}$ *the square* $Q \in \mathscr{Q}_n$ *such that* $Q \ni p$ *is called a* discrete vertex *of* T*;*

(ii) for each edge $e \in \{[ab],[bc],[ca]\}$*, the set of squares* $Q \in \mathscr{Q}_n$ *such that* $Q \cap e \neq \emptyset$ *and* Q *is not a discrete vertex is called a* discrete (open) edge *of the triangle* T*;*

(iii) the set of squares $Q \in \mathscr{Q}_n$ *such that* $Q \cap T \neq \emptyset$ *and* Q *is neither a discrete vertex nor belongs to a discrete open edge is called a* discrete open triangle.

5.3.2. Piecewise polynomials functions on triangulations

We take $S^n = \{1, \cdots, n\}^2$ and the set of fragments $\mathscr{R}^n$ is given as the set of discrete vertices, open edges and open triangles

$$\mathscr{R}^n = S^n \cup \{([ab]) : a, b \in S^n\} \cup \{([abc]) : a, b, c \in S^n\} .$$

We let $\mathfrak{P}^n$ then be the collection of partitions of S^n into discrete triangles, obtained from a continuous triangulations, and assuming that there is a rule deciding to which triangle discrete open segments and discrete vertices belong. Each such discrete triangle is then the union of elementary digital sets in $\mathscr{R}^n$. We remark that $|\mathscr{R}^n| = n + n(n-1)/2 + n(n-1)(n-2)/6$ and therefore $|\mathscr{R}^n| \sim n^3/6$. Like in the one-dimensional case, as described in Section 5.1, we choose the finite dimensional linear subspace $\mathscr{F}_p \subset L^2([0,1))$ of polynomials of maximal degree p. The induced segmentation classes $\mathfrak{S}^n(\mathfrak{P}^n, \mathfrak{F}^n)$ consist of piecewise polynomial functions relative to partitions in $\mathfrak{P}^n$.

We have the following approximation lemma

Lemma 8 *Let* $f \in \mathscr{C}^\alpha([0,1]^2)$*, with* $p < \alpha < p+1$*. There is* $C > 0$ *such that for all* $k \leq n \in \mathbb{N}$*, there is* $(\mathscr{P}_k^n, h_k^n) \in \mathfrak{S}^n$*, such that* $|\mathscr{P}_k^n| \leq k$ *and which satisfies*

$$\|f - \iota^n h_k^n\| \leq C \cdot \left(\frac{1}{k^{\alpha/2}} + \left(\frac{k}{n}\right)^{1/2} \right). \tag{36}$$

Proof. We first use classical aproximation theory which tells us the existence of a function $h_k : [0,1]^2 \mapsto \mathbb{R}$, piecewise polynomial relatively to a triangulation with k triangles and such that the error on the whole domain is bounded by

$$\|f - h_k\| \leq \frac{C}{k^{\alpha/2}}.$$

As in the 1-D case we split $[0,1)^2$ into the union J_n^k of those squares in $\mathscr{Q}_n$ which do not meet the continuous triangulation, and K_n^k the set of such squares meeting the triangulation, i.e. which intersects with some edge of the triangulation. For each small square $Q \in \mathscr{Q}_n$ and $Q \subset K_n^k$, the following estimate holds:

$$\|h_k - \iota^n \delta^n h_k\|^2_{L^2(Q)} \leq \frac{C}{n^2} \text{ for any } Q \in K_n^k, \text{ and some constant } C > 0$$

and there are at most $3 \cdot \sqrt{2}kn$ such squares. Altogether we obtain:

$$\|h_k - \iota^n \delta^n h_k\|_{L^2(K_n^k)} \leq \frac{Ck^{1/2}}{n^{1/2}}, \text{ for some constant } C > 0.$$

Now for each square $Q \in \mathscr{Q}_n$ and $Q \subset J_n^k$, an argumentation similar to that in the $1D$-proof yields

$$\|h_k - \iota^n \delta^n h_k\|_{L^2(J_k^n)} \leq \frac{C}{n}.$$

This completes the proof. □

Due to Lemma 8, (15) is satisfied: a function in $\mathscr{C}^\alpha$ satisfies (15) with $\rho = 1/2$ and $F_n = n^{1/2}$ and therefore Theorem 5 applies.

5.3.3. Continuous linear splines

We turn now to the more subtle case of continuous linear splines on Delaunay triangulations. Anisotropic Delaunay triangulations have been recently applied successfully to the design of a full image compression/decompression scheme, L. DEMARET et al. [10], L. DEMARET et al. [14]. Here we investigate the behavior of such triangulation schemes in the context of image estimation.

To this end, we first introduce the associated function space in the continuous setting. We restrict the discussion to the case of piecewise affine functions, i.e. $p = 1$.

Definition 5 *Let $\mathcal{T}$ be a conforming triangulation of $[0,1]^2$. Let*

$$\mathcal{S}^0_{\mathcal{T}} = \left\{ f \in \mathscr{C}\left([0,1]^2\right) \;:\; f\big|_T \in \mathscr{F}_1, T \in \mathcal{T} \right\},$$

be the set of piecewise affine and continuous functions on $\mathcal{T}$.

The following piecewise smooth functions generalise the horizon functions from (31).

Definition 6 *Let* $\alpha \in (1,2)$ *and* $g \in \mathscr{C}^\alpha([0,1])$*. Let* S^+ *and* S^- *be two subdomains defined as in (30). A* generalised α-horizon function *is an element of the set*

$$\mathscr{H}^{\alpha,2}([0,1]^2) := \left\{ f \in L^2([0,1]^2) \mid f|_{S^+}, f|_{S^-} \in W^{\alpha,2}(S^\pm) \right\}$$

where $W^{\alpha,2}(S^\pm)$ *is the Sobolev space of regularity* α *relative to the* L^2*-norm on* $S^\pm$.

In order to obtain convergence rates of the triangulation-based estimators for this class of functions we need the following recent result, Thm.4 in L. DEMARET and A. ISKE [13]:

Theorem 8 *Let* f *be an* α*-horizon function in* Hor_1^α*, with* $\alpha \in (1,2)$*, such that* $f|_{S^\pm} \in W^{\alpha,2}(S^\pm)$*. Then there is* $C > 0$*, such that for all* $k \in \mathbb{N}$ *there is a Delaunay triangulation* $\mathcal{D}_k$ *with* k *vertices and such that*

$$\|f - \pi_{\mathcal{S}^0_{\mathcal{D}_k}} f\|_{L^2([0,1]^2)} \leq \frac{C}{k^{\alpha/2}}.$$

Using arguments as in the proof of Lemma 8, we obtain the following lemma:

Lemma 9 *Let* $f \in \mathscr{H}^{\alpha,2}([0,1]^2)$*, with* $1 < \alpha < 2$ *there is* $C > 0$ *such that for all* $k \leq n \in \mathbb{N}$*, there is* $(\mathscr{P}_k^n, h_k^n)$*, such that* $\mathscr{P}_k^n \in \mathfrak{P}^n$ *is a discretization of a continuous Delaunay triangulation* $\mathcal{D}_k$*,* $|\mathscr{P}_k^n| \leq k$*,* $h_k^n = \delta^n h_k$*, where* $h_k \in \mathcal{S}^0_{\mathcal{D}_k}$ *and which satisfies*

$$\|f - \iota^n h_k^n\| \leq C \cdot \left(\frac{1}{k^{\alpha/2}} + \frac{k^{1/2}}{n^{1/2}} \right).$$

The previous machinery cannot be applied directly without an explanation: since we are dealing with the space of continuous linear splines, our scheme is not properly a projective $\mathscr{F}$-segmentation class. However, for each fixed partition, $\mathscr{P} \in \mathfrak{P}$ with elements in $\mathscr{R}^n$, $\mathcal{S}^0_{\mathcal{T}}$ a subspace of $\mathscr{F}_{\mathscr{P}}$. Observe that all arguments in Lemma 1 remain valid if we replace $\mathscr{F}_{\mathscr{P}}$ by subspaces and consider also the minimisation of the functional H^n_γ over functions in these subspaces. We can thus apply Theorem 5 to obtain the equivalent of Theorem 6.

Theorem 9 *Let $\alpha \in (1,2)$ and let f be a generalized horizon function in $\mathscr{H}^\alpha([0,1]^2)$. Let further assume that noise in* (3) *is such that (H1.2) holds. Assume further that γ_n satisfy (H1.3) with $\kappa = 3$. Then*

$$\|\hat{f}^n_{\gamma_n} - f\|^2 = O\left(\gamma_n^{\frac{\alpha}{\alpha+1}}\right) + O\left(n^{-\frac{\alpha}{\alpha+1}}\right) \text{ for almost all } \omega \in \Omega, \tag{37}$$

where $\hat{f}^n_{\gamma_n}$ is the Delaunay estimator.

Proof. We check the assumptions in Theorem 5. Since $|\mathscr{R}^n|$ is of the order $(n^2)^3$, Hypothesis *(H1.1)* holds with $\kappa = 3$. Hypothesis *(H1.2)* and *(H1.3)* were required separately. Finally, (15) holds with $\varrho = 1/2$ and $F_n = n^{1/2}$ by Lemma 9. This completes the proof. □

Remark 7 *Similarly to Remark 6 and choosing γ_n of the order $\ln n/n^2$, estimate* (37) *reads*

$$\|\hat{f}^n_{\gamma_n} - f\|^2 = O\left(\frac{(\ln n)^{\frac{2\alpha}{\alpha+1}}}{n^{\frac{2\alpha}{\alpha+1}}}\right) + O\left(\frac{1}{n^{\frac{\alpha}{\alpha+1}}}\right) \text{ for almost all } \omega \in \Omega.$$

As in Remark 6, we observe that the discretization error asymptotically dominates over the other term: the discussion of Remark 6. Again, neglecting the discretization term, we have obtained optimal rates for a class of piecewise smooth images by using estimation by Delaunay triangulations and where we used the numbers of vertices as penalization.

Whereas the first term on the right-hand size consists of the best compromise between approximation and noise removal, the second term on the right-hand size corresponds to the discretization error. Note that, in contrast to the $1D$-case the discretization error asymptotically dominates the first term. This is related to the piecewise constant nature of the discretization. In concrete applications, this may severly limit the actual quality of the estimation. Neglecting this discretization problem, the decay rates given by (35) are the usual optimal rates for the function class under consideration.

On the right column of Fig. 3, estimators by Delaunay triangulation are shown, for the same noisy horizon function as in the wedgelet case.

The rates in Theorem 9 are, up to a logarithmic factor, similar to the minimax rates obtained in E. Candès and D. Donoho [8] with curvelets for $\alpha = 2$ and more recently in C. Dossal et al. [17] with bandelets for general α. This is in contrast to isotropic approximation methods, e.g. shrinkage of tensor product wavelet coefficients, which only attain the rate for $\alpha = 1$.

References

1. L. Birgé and P. Massart. From model selection to adaptive estimation. *Festschrifft for Lucien Le Cam: Research Papers in Probability and Statistics*, pages 55–87, 1997.
2. L. Birgé and P. Massart. Minimal penalties for gaussian model selection. *Probability theory and related fields*, 138(1):33–73, 2007.
3. L. Boysen, A. Kempe, V. Liebscher, A. Munk, and O. Wittich. Consistencies and rates of convergence of jump-penalized least squares estimators. *Ann. Statist.*, 37(1):157–183, 2009.
4. L. Boysen, V. Liebscher, A. Munk, and O. Wittich. Scale space consistency of piecewise constant least squares estimators - another look at the regressogram. *IMS Lecture Notes-Monograph Series*, 55:65–84, 2007.
5. J. Bresenham. Algorithm for computer control of a digital plotter. *IBM Systems Journal*, 4:25–30, 1965.
6. V.V. Buldygin and Yu.V. Kozachenko. *Metric Characterization of Random Variables and Random Processes*. American Mathematical Society, Providence, Rhode Island, 2000.
7. E. Candès. Modern statistical estimation via oracle inequalities. *Acta Numerica*, pages 257–325, 2005.
8. E. Candès and D. Donoho. New tight frames of curvelets and optimal representations of objects with piecewise-C2 singularities. *Comm. Pure Appl. Math.*, 57:219–266, 2002.
9. Y.S. Chow. Some convergence theorems for independent random variables. *Ann. of Math. Statist.*, 35:1482–1493, 1966.
10. L. Demaret, N. Dyn, and A. Iske. Image compression by linear splines over adaptive triangulations. *Signal Processing Journal*, 86:1604–1616, 2006.
11. L. Demaret, F. Friedrich, V. Liebscher, and G. Winkler. Complexity l^0-penalized m-estimation: Consistency in more dimensions. 2013. arXiv preprint arXiv:1301.5492, submitted.
12. L. Demaret and A. Iske. Anisotropic triangulation methods in image approximation. In E.H. Georgoulis, A. Iske, and J. Levesley, editors, *Algorithms for Approximation*, pages 47–68. Springer-Verlag, Berlin, 2010.

13. L. Demaret and A. Iske. Optimal n-term approximation by linear splines over anisotropic delaunay triangulations. *preprint*, 2012.
14. L. Demaret, A. Iske, and W. Khachabi. Contextual image compression from adaptive sparse data representations. In *Proceedings of SPARS'09, April 2009, Saint-Malo*, 2009.
15. R. DeVore and G. Lorentz. *Constructive Approximation*. Grundlehren der mathematischen Wissenschaften. Springer Verlag, Heidelberg, 1993.
16. D. Donoho. Wedgelets: Nearly minimax estimation of edges. *Ann. Statist.*, 27(3):859–897, 1999.
17. C. Dossal, S. Mallat, and E. Le Pennec. Bandelets image estimation with model selection. *Signal Processing*, 91(12):2743–2753, 2011.
18. T. Dupont and R. Scott. Polynomial approximation of functions in Sobolev spaces. *Mathematics of Computation*, 34(150):441–463, 1980.
19. M. Elad. *Sparse and Redundant Representations: From Theory to Applications in Signal and Image Processing*. Springer Verlag, 2010.
20. F. Friedrich. *Complexity Penalized Segmentations in 2D - Efficient Algorithms and Approximation Properties*. PhD thesis, Munich University of Technology, Institute of Biomathematics and Biometry, National Research Center for Environment and Health, Munich, Germany, 2005.
21. F. Friedrich, L. Demaret, H. Führ, and K. Wicker. Efficient moment computation over polygonal domains with an application to rapid wedgelet approximation. *SIAM J. Scientific Computing*, 29(2):842–863, 2007.
22. F. Friedrich, A. Kempe, V. Liebscher, and G. Winkler. Complexity penalized M-estimation: Fast computation. *JCGS*, 17(1):1–24, 2008.
23. S. Geman and D. Geman. Stochastic relaxation, Gibbs distributions, and the Bayesian restoration of images. *IEEE Trans. PAMI*, 6:721–741, 1984.
24. L. Györfi, M. Kohler, A. Krzyzak, and Harro Walk. *A distribution-free theory of nonparametric regression*. Springer Series in Statistics, 2002.
25. E. Ising. Beitrag zur Theorie des Ferromagnetismus. *Z. Physik*, 31:253, 1925.
26. J.P. Kahane. Séminaire de Mathématiques supérieures. Technical report, Université de Montréal, 1963.
27. A. Kempe. *Statistical analysis of discontinuous phenomena with Potts functionals*. PhD thesis, Institute of Biomathematics and Biometry, National Research Center for Environment and Health, Munich, Germany, 2004.

28. R. Korostelev and Tsybakov. *Minimax Theory of Image Reconstruction*. Lecture Notes in Statistics 82. Springer, New York, 1993.
29. W. Lenz. Beiträge zum Verständnis der magnetischen Eigenschaften in festen Körpern. *Physikalische Zeitschrift*, 21:613–615, 1920.
30. V. Liebscher and G. Winkler. A Potts model for segmentation and jump-detection. In V. Benes, J. Janacek, and I. Saxl, editors, *Proceedings S4G International Conference on Stereology, Spatial Statistics and Stochastic Geometry, Prague June 21 to 24, 1999*, pages 185–190, Prague, 1999. Union of Czech Mathematicians and Physicists.
31. E. Le Pennec and S. Mallat. Sparse geometrical image approximation using bandelets. *IEEE Trans. Image Processing*, 14(4):423–438, 2005.
32. V.V. Petrov. *Sums of Independent Random Variables*. Springer Verlag, New York, 1975.
33. R.B. Potts. Some generalized order-disorder transitions. *Proc. Camb. Phil. Soc.*, 48:106–109, 1952.
34. J.W. Tukey. Curves as parameters, and touch estimation. In *Proc. 4th Berkeley Sympos. Math. Statist. and Prob.*, volume I, pages 681–694, Berkeley, Calif., 1961. Univ. California Press.
35. R. Willett and R. Nowak. Platelets: a multiscale approach for recovering edges and surfaces in photon-limited medical imaging. *IEEE Transations in Medical Imaging*, 22(3):332–350, 2003.
36. G. Winkler. *Image Analysis, Random Fields and Markov Chain Monte Carlo Methods. A Mathematical Introduction*, volume 27 of *Stochastic Modelling and Applied Probability*. Springer Verlag, Berlin, Heidelberg, New York, second edition, 2003. Completely rewritten and revised, Corrected 3rd printing 2006.
37. G. Winkler, A. Kempe, V. Liebscher, and O. Wittich. Parsimonious segmentation of time series by Potts models. In D. Baier and K.-D. Wernecke, editors, *Innovations in Classification, Data Science, and Information Systems. Proc. 27th Annual GfKl Conference, University of Cottbus, March 12 - 14, 2003.*, Studies in Classification, Data Analysis, and Knowledge Organization, pages 295–302, Heidelberg-Berlin, 2004. Gesellschaft für Klassifikation, Springer-Verlag.

38. G. Winkler and V. Liebscher. Smoothers for discontinuous signals. *J. Nonpar. Statist.*, 14(1-2):203–222, 2002.
39. G. Winkler, O. Wittich, V. Liebscher, and A. Kempe. Don't shed tears over breaks. *Jahresbericht der Deutschen Mathematiker-Vereinigung*, 107(2):57–87, 2005.
40. O. Wittich, A. Kempe, G. Winkler, and V. Liebscher. Complexity penalized least squares estimators: Analytical results. *Mathematische Nachrichten*, 281 (4):1–14, 2008.

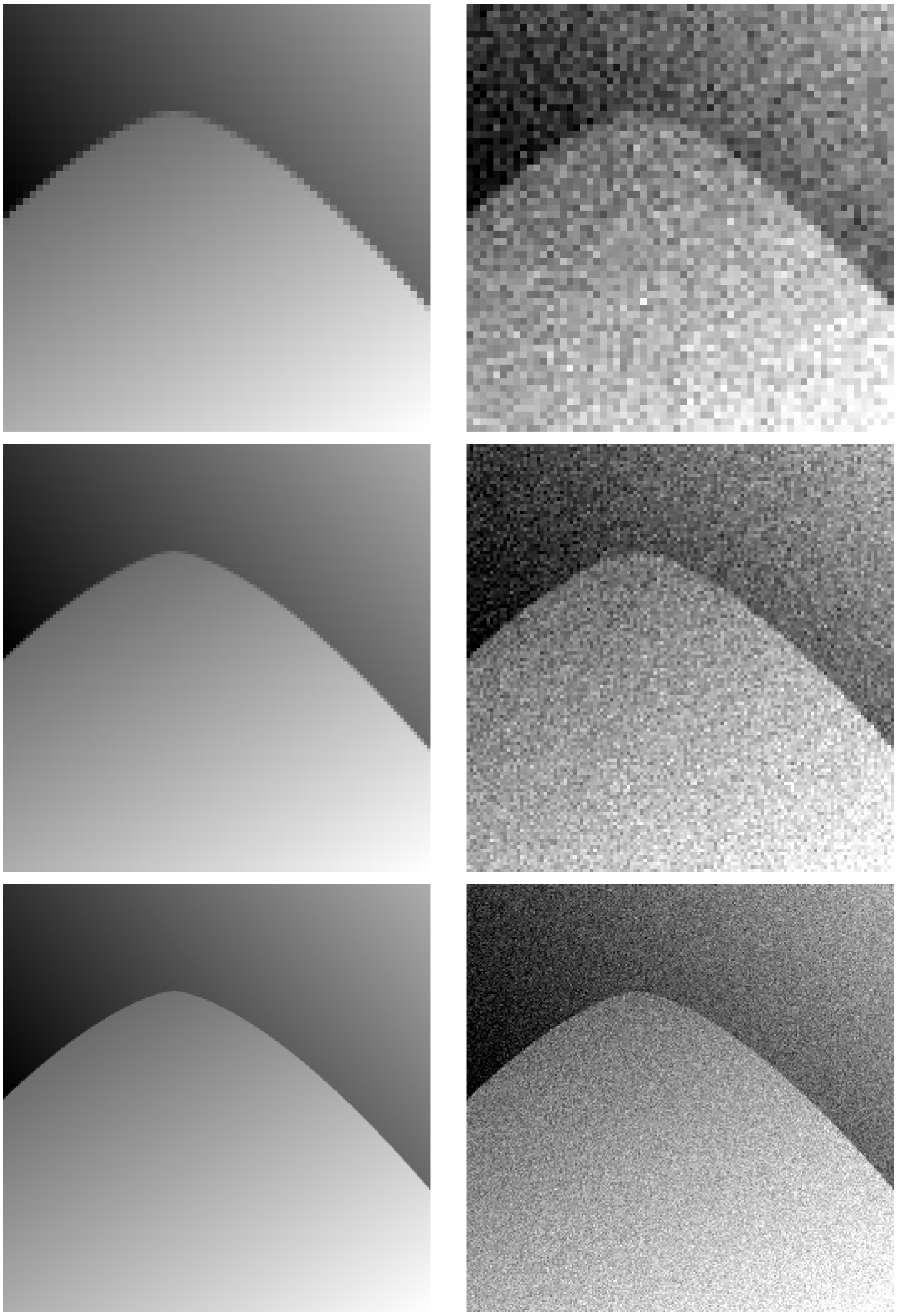

Figure 2. Left: $\delta^n f$, for $n = 64, 128, 256$, respectively, where f is a horizon function, according to Definition 2. Here, the horizon boundary is in $\mathscr{C}^\alpha((0,1))$ and $\alpha = 1.5$. Right: Respective noisy images $\delta^n f + \xi^n$.

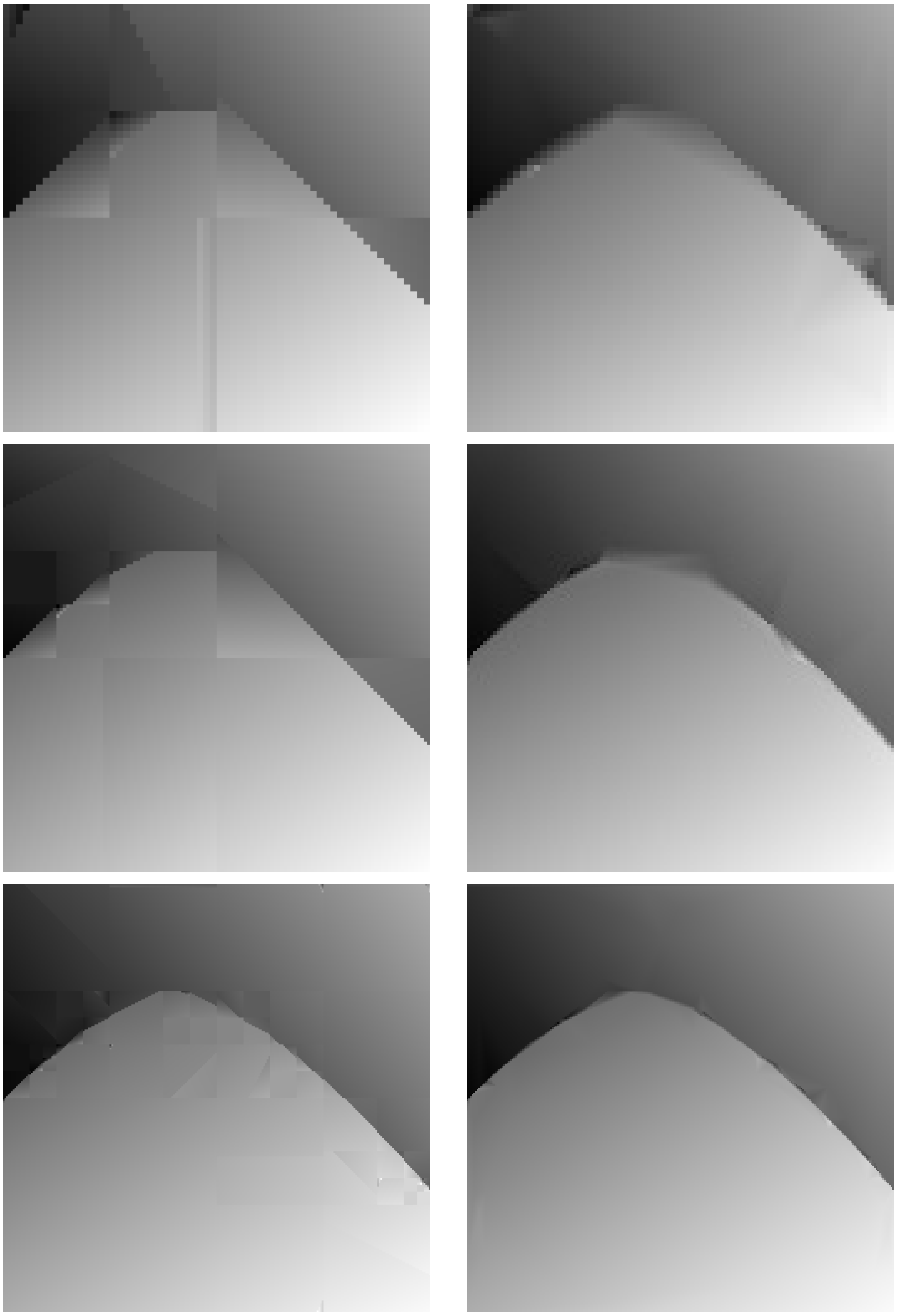

Figure 3. Estimators of the noisy images of Fig 2. Left: piecewise linear wedgelet estimator. Right: piecewise linear and continuous Delaunay estimators.