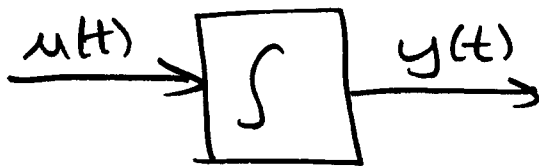


## The Superposition Principle:

The principle has 3 different aspects:

A) SISO system, no initial conditions:



We perform 2 experiments:

$$(1) u(t) = u_1(t) \Rightarrow y(t) = y_1(t)$$

$$(2) u(t) = u_2(t) \Rightarrow y(t) = y_2(t)$$

Now, we perform a third experiment:

$$(3) u(t) = c_1 \cdot u_1(t) + c_2 \cdot u_2(t)$$

✓ if and only if

IFF the system is linear

$$\Rightarrow y(t) = c_1 \cdot y_1(t) + c_2 \cdot y_2(t)$$

$$\forall u_1(t), u_2(t)$$

The system response to a mixture of the two input signals  $u_1(t)$  and  $u_2(t)$  is a mixture of the system responses to the individual signals.

The IF part is easy to prove:

$$y_1(t) = \mathcal{L}^{-1} \{ Y_1(s) \}$$

where:  $Y_1(s) = G(s) \cdot U_1(s)$

and:  $U_1(s) = \mathcal{L} \{ u_1(t) \}$

Similarly:

$$y_2(t) = \mathcal{L}^{-1} \{ G(s) \cdot \mathcal{L} \{ u_2(t) \} \}$$

Hence:

$$u(t) = c_1 \cdot u_1(t) + c_2 \cdot u_2(t)$$

$$U(s) = c_1 \cdot U_1(s) + c_2 \cdot U_2(s)$$

$$\Rightarrow Y(s) = G(s) \cdot U(s)$$

-45-

$$\begin{aligned}\Rightarrow Y(s) &= G(s) \cdot [c_1 \cdot U_1(s) + c_2 \cdot U_2(s)] \\ &= c_1 \cdot [G(s) \cdot U_1(s)] + c_2 \cdot [G(s) \cdot U_2(s)] \\ &= c_1 \cdot Y_1(s) + c_2 \cdot Y_2(s)\end{aligned}$$

$$y(t) = c_1 \cdot y_1(t) + c_2 \cdot y_2(t)$$

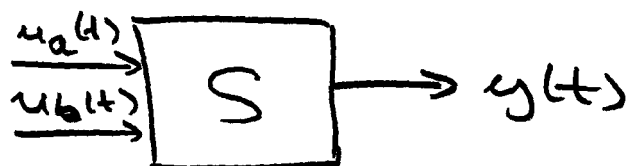
q.e.d.

The IFF part is not so easy to prove, and we won't even try.

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B) MISO system, no initial conditions

Given a multi-input/single-output (MISO) system with zero initial conditions, e.g.



We again perform 2 experiments:

$$(i) \quad \left| \begin{array}{l} u_a(t) = u_1(t) \\ u_b(t) = \phi \end{array} \right| \Rightarrow y(t) = y_a(t)$$

$$(ii) \quad \left| \begin{array}{l} u_a(t) = \phi \\ u_b(t) = u_2(t) \end{array} \right| \Rightarrow y(t) = y_b(t)$$

We now perform a third experiment:

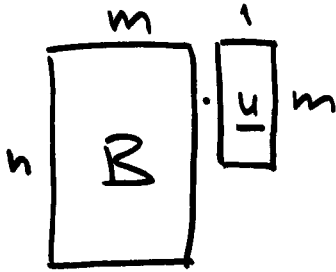
$$(iii) \quad \left| \begin{array}{l} u_a(t) = c_1 \cdot u_1(t) \\ u_b(t) = c_2 \cdot u_2(t) \end{array} \right|$$

IFF the system is linear

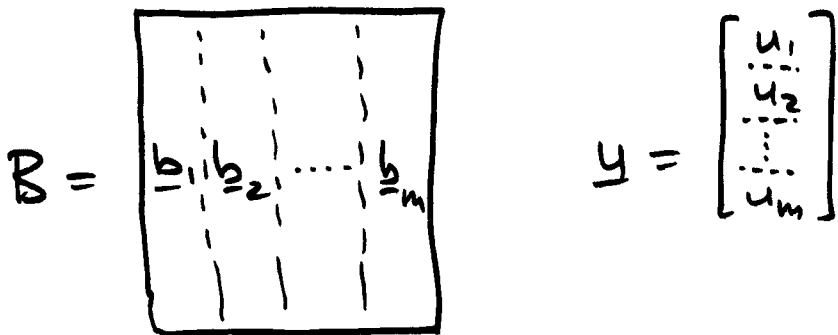
$$\Rightarrow y(t) = c_1 \cdot y_a(t) + c_2 \cdot y_b(t)$$

The proof of the IF part is easy. It follows directly from matrix-vector calculus:

$$y(t) = \underline{C}' \int_{0^-}^t e^{A(t-\tau)} \cdot \underbrace{B \cdot \underline{u}(\tau)} dt$$



Let  $B = [\underline{b}_1, \underline{b}_2, \dots, \underline{b}_m]$  ;  $\underline{u} = [u_1; u_2; \dots; u_m]$



$$\Rightarrow B \cdot \underline{u} = \underline{b}_1 \cdot u_1 + \underline{b}_2 \cdot u_2 + \dots + \underline{b}_m \cdot u_m$$

$$\Rightarrow y(t) = \underline{C}' \int_{0^-}^t e^{A(t-\tau)} \cdot (\underline{b}_1 \cdot u_1(\tau) + \underline{b}_2 \cdot u_2(\tau) + \dots + \underline{b}_m \cdot u_m(\tau)) \cdot d\tau$$

$$\equiv \underline{C}' \int_{0^-}^t e^{A(t-\tau)} \underline{b}_1 \cdot u_1(\tau) d\tau + \underline{C}' \int_{0^-}^t e^{A(t-\tau)} \underline{b}_2 \cdot u_2(\tau) d\tau + \dots + \underline{C}' \int_{0^-}^t e^{A(t-\tau)} \underline{b}_m \cdot u_m(\tau) d\tau$$

i.e., the response is indeed a superposition of the responses of the individual signals.

The IFF part is again not so easy to prove.

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C) SISO system with initial conditions



We again perform 2 experiments:

$$(i) \left| \begin{array}{l} u(t) = u_1(t) \\ x_0 = \emptyset \end{array} \right| \Rightarrow y(t) = y_u(t)$$

$$(ii) \left| \begin{array}{l} u(t) = \emptyset \\ x_0 = x_0 \end{array} \right| \Rightarrow y(t) = y_x(t)$$

We now perform a third experiment:

$$(iii) \left| \begin{array}{l} u(t) = c_1 \cdot u_1(t) \\ \underline{x}_0 = c_2 \cdot \underline{x}_{0,1} \end{array} \right|$$

IFF the system is linear:

$$\Rightarrow y(t) = c_1 \cdot y_u(t) + c_2 \cdot y_x(t)$$

The proof of the IF portion follows directly from the convolution integral:

$$y(t) = \underline{c}' e^{At} \cdot \underline{x}_0 + \underbrace{g(t) * u(t)}_{\text{Superposition}}$$

The IFF part is again much more difficult to prove.