

Zorua: A Holistic Approach to Resource Virtualization in GPUs



Session 2A
Monday, 5:20 PM

Nandita Vijaykumar

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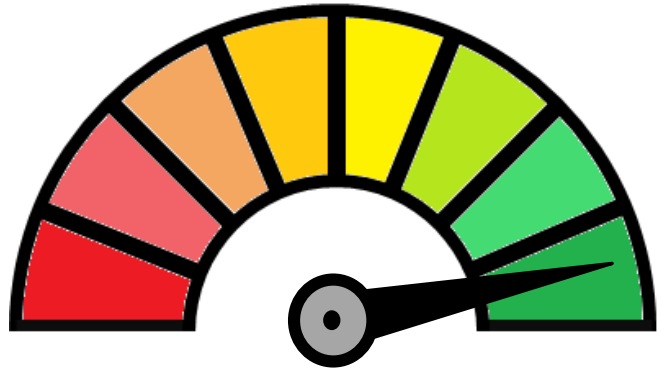
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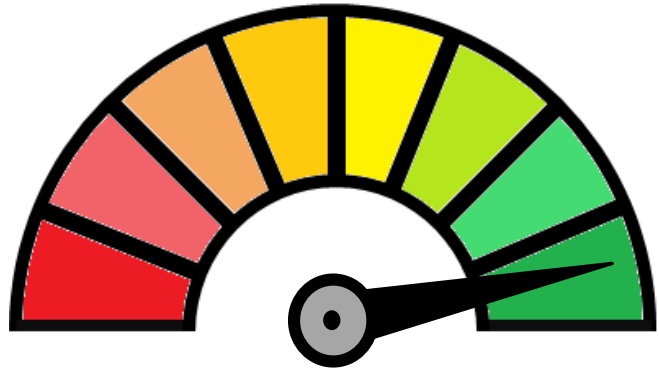

**UNIVERSITY
of VIRGINIA**

**WILLIAM
& MARY**

ETH zürich



**High
Performance**



**High
Performance**



GPUs

```
__global__ void CUDAkernel2DCT(float *dst,  
float *src, int I){  
    int OffsThreadInRow = threadIdx.y * B +  
threadIdx.x;  
    for(unsigned int i = 0; i < B; i++)  
        bl_ptr[i * X] = src[i * I];  
    __syncthreads();  
  
    CUDASubroutineInplaceDCTvector(...);  
    __syncthreads();  
  
    CUDASubroutineInplaceDCTvector(...);  
  
    for(unsigned int i = 0; i < B; i++)  
        dst[i * I] = bl_ptr[i * X]; }
```

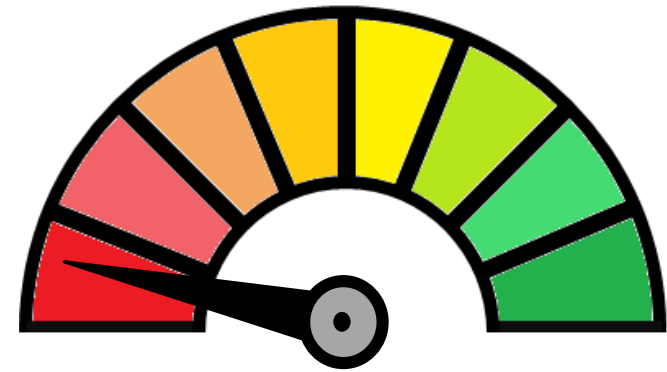


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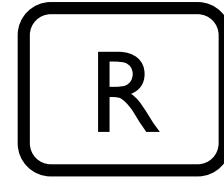


**Low
Performance!**

**The *programmer* has to statically allocate
3 major resources:**

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3 major resources:**

- **Registers**



The **programmer** has to statically allocate
3 major resources:

- **Registers** R
- **Scratchpad Memory** S

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- **Thread Slots** T

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3 major resources:

- **Registers** **R**
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- **Thread Slots** **T**

Imperfect Allocation ⇒ Low Performance

```
__global__ void CUDAkernel12DCT(float *dst,
float *src, int I){
    int OffsThreadInRow = threadIdx.y * B +
threadIdx.x;
    for(unsigned int i = 0; i < B; i++)
        bl_ptr[i * X] = src[i * I];
    __syncthreads();

    CUDASubroutineInplaceDCTvector(...);
    __syncthreads();

    CUDASubroutineInplaceDCTvector(...);

    for(unsigned int i = 0; i < B; i++)
        dst[i * I] = bl_ptr[i * X]; }
```



Tune Code

FIX: *Usage of Registers, Scratchpad and Thread Slots*

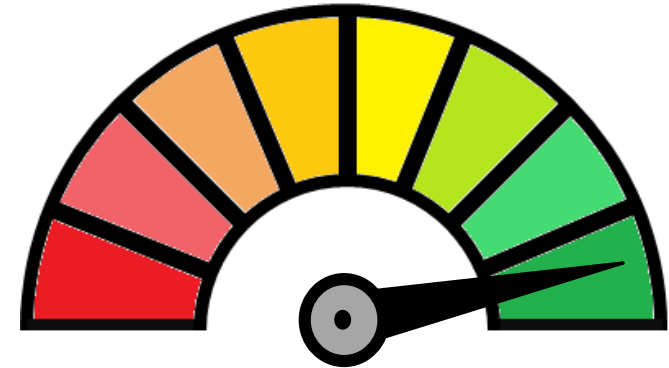
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```



R

S

T



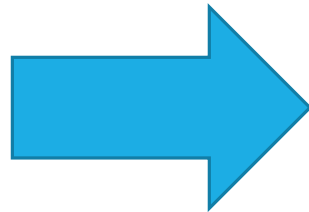
High
Performance

Problem: Programming Effort



GPU 1

```
__global__ void CUDAKernelI2DCT(float *dst,  
float *src, int I){  
    int OffsThreadInRow = threadIdx.y * B +  
    threadIdx.x;  
    for(unsigned int i = 0; i < B; i++){  
        bl_ptr[i * X] = src[i * I];  
        __syncthreads();  
  
        CUDASubroutineInplaceDCTvector(...);  
        __syncthreads();  
  
        CUDASubroutineInplaceDCTvector(...);  
  
        for(unsigned int i = 0; i < B; i++){  
            dst[i * I] = bl_ptr[i * X]; }  
}
```



GPU 2

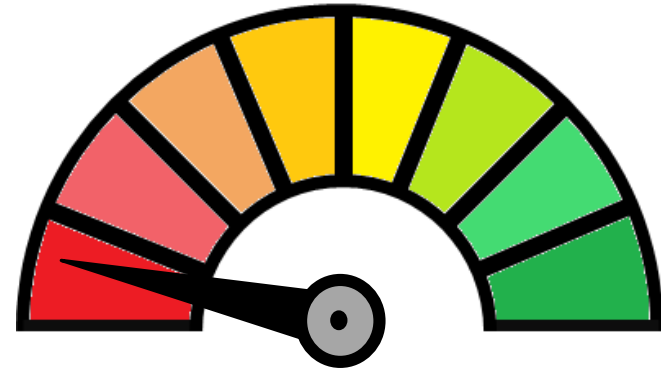


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__global__ void CUDAkernel2DCT(float *dst,
float *src, int I){
    int OffsThreadInRow = threadIdx.y * B +
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    for(unsigned int i = 0; i < B; i++)
        bl_ptr[i * X] = src[i * I];
    __syncthreads();

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    __syncthreads();

    CUDASubroutineInplaceDCTvector(...);

    for(unsigned int i = 0; i < B; i++)
        dst[i * I] = bl_ptr[i * X]; }
```



**Low
Performance!**

Problem: Performance Portability

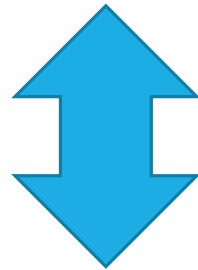
***Programmer-specified* resource allocation
leads to 3 key issues with:**

- ***Programming ease***
- ***Performance portability***
- ***Performance for optimized code***

Our Approach

Decouple

Programmer-specified resource usage



Allocation in the hardware



Zorua:

***A Framework to Virtualize
On-chip Resources in GPUs***

Zorua: A Holistic Approach to Resource Virtualization in GPUs



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