7th Homework

- In this homework, we shall model and simulate a discontinuous system as well as train the incorporation of tabular functions.
- We shall first model an electrical oscillatory circuit containing a tunnel diode.
- We shall then model a fly-back electronic power converter circuit with current overprotection.



- Free-running tunnel diode circuit
- Pulsed tunnel diode circuit
- <u>Fly-back electronic power converter</u> <u>circuit</u>



Free-running Tunnel Diode Circuit I

• Given the following electronic circuit:



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Free-running Tunnel Diode Circuit II

- Let us set $U_{tr} = 0$. We select a resistor with a value of $R = 25 \Omega$. We choose a DC bias of $U_0 = 0.48 V$.
- Create a bond graph (without wrapping) of the circuit. Use causal bonds whenever possible.
- Create a model *T3* representing the tunnel diode. The tabular function is incorporated by dragging the corresponding table-lookup block into the diagram window.
- Use Matlab to save the table onto a binary file, and reference that table from within the parameter window of the table-lookup block. Make sure to assign the correct causality to the table-lookup function. You can determine the correct causality from the bond graph of the overall circuit.



Free-running Tunnel Diode Circuit III

- Now create a model of the overall circuit (without wrapping) in Dymola using the *BondLib* library as well as the previously coded *T3* model.
- Simulate the circuit across *0.2 msec* of simulated time.
- Plot the current through the tunnel diode.
- Interpret the results obtained.



Pulsed Tunnel Diode Circuit I

• In a second experiment, we include the following pulsed trigger signal, U_{tr} .



You can easily create the trigger voltage out of the superposition of two of the pulsed voltage sources provided in the standard bond graph library.

November 1, 2012





Pulsed Tunnel Diode Circuit II

- For this experiment, we select a resistor with a value of $R = 200 \Omega$. We now choose a DC bias of $U_0 = 1.075 V$.
- Simulate the modified circuit across *0.2 msec* of simulated time.
- Plot the current through the tunnel diode.
- Interpret the results obtained.



Fly-back Power Converter Circuit I

• Given the electronic circuit:



• The purpose is to create an inductor current that is approximately sinusoidal.

November 1, 2012



Fly-back Power Converter Circuit II

- To this end, we use pulse width modulation.
- The four switches are controlled in such a way that sometimes V_{in} is being applied to the *RL* circuit, and at other times -*Vin*.
- The logic is explained in the graph to the right.





Fly-back Power Converter Circuit III

- If the sine-wave signal is larger than the triangular signal, switches #1 and #4 must be closed, whereas switches #2 and #3 must be opened.
- If the sine-wave signal is smaller than the triangular signal, switches #2 and #3 must be closed, whereas switches #1 and #4 must be opened.



Fly-back Power Converter Circuit IV

- We also want to implement a over-current protection circuit.
- When the inductor current becomes larger than 11.05 *A*, switches #2 and #4 must be closed, and switches #1 and #3 must be opened, irrespective of what the previous logic indicated.
- When the inductor current becomes smaller than *10.95A*, the previous logic takes precedence once again.
- The hysteresis around the threshold current of 11.0 A is necessary to avoid chattering.



Fly-back Power Converter Circuit V

- Without the hysteresis, the switches would switch back and forth with infinite frequency. This phenomenon is called chattering.
- Create a bond graph model of the fly-back converter circuit. Use causal bonds wherever the causality is fixed, and use a-causal bonds elsewhere.
- Make use of four "leaky" switches to avoid divisions by zero.
- Program the logic of the four switches graphically using the standard *Modelica* blocks library.



Fly-back Power Converter Circuit VI

- Simulate the circuit across 1 sec of simulated time using $R = 0.6 \Omega$ and L = 100 mH.
- Plot the inductor current over the entire period, and also over two smaller time windows, namely at an early period, when the over-current protection is active, and during steady-state operation.

